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Bifurcations of normally parabolic tori in Hamiltonian systems

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Abstract

We consider perturbations of integrable Hamiltonian systems in the neighbourhood of normally parabolic invariant tori. Under appropriate transversality conditions the tori in the unperturbed system bifurcate according to a (generalized) cuspid catastrophe. Combining techniques of KAM theory and singularity theory, we show that such bifurcation scenarios survive the perturbation on large Cantor sets. Applications to rigid body dynamics and forced oscillators are pointed out.

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1. Setting of the problem

KAM theory is usually committed in the context of nearly integrable Hamiltonian systems. The, by now, classical part of the theory (see Pöschel (1982)), establishes the persistence of quasi-periodic invariant tori of Lagrangian type under small perturbations away from integrability. Also, persistence of normally hyperbolic and normally elliptic tori has been studied, (cf Pöschel (1989), Broer *et al* (1990), Rüssmann (2001)). In all cases the persistent tori constitute subsets of the phase space that have a Cantor like structure and a relatively large Hausdorff measure of twice the torus dimension. For an up to date overview of these and related results, see Broer *et al* (1996a) and Rüssmann (2001). Regarding the (quite different) theory of invariant tori whose dimension exceeds the number of degrees of freedom, see Broer *et al* (1996a), Sevryuk (2003) and references therein. For a non-perturbative approach to KAM theory, see de la Llave *et al* (2005).

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The Cantor-like structure is imposed by the structural instability of resonant invariant tori. Indeed, in the case there are integer relations $\sum k_i \omega_i = 0$ between the internal frequencies $\omega_1, \dots, \omega_n$, the torus tends to break up under non-integrable perturbations (see Sevryuk (2003) and references therein). Diophantine conditions

$$|k_1 \omega_1 + \dots + k_n \omega_n| \geq \frac{\gamma}{|k|^\tau} \quad \forall_{k \in \mathbb{Z}^n \setminus \{0\}} \quad (1.1)$$

with $\tau > n - 1$ and $\gamma > 0$ yield a strong form of non-resonance that provides the necessary estimates during a KAM iteration. For Lagrangian tori the number of internal frequencies is equal to the number of degrees of freedom, and (1.1) is sufficient to prove persistence; the usual Kolmogorov condition (5.1) ensures that these Diophantine conditions are satisfied by the majority of tori. Lower dimensional tori with hyperbolic normal behaviour become Lagrangian on a centre manifold and (1.1) again yields persistence.

Normally elliptic invariant tori have normal frequencies $\Omega, \Lambda, \dots$ that may lead to normal-internal resonances of the form

$$\Omega = \sum_{i=1}^n k_i \omega_i \quad (1.2)$$

and of the forms

$$\ell_1 \Omega + \ell_2 \Lambda = \sum_{i=1}^n k_i \omega_i \quad (1.3)$$

with $k \in \mathbb{Z}^n$ and $\ell \in \mathbb{Z}^2$ satisfying $|\ell| = 2$. As shown in Bourgain (1994, 1997) and Xu and You (2001), the latter resonances (1.3) do not preclude the persistence of the tori in question; in addition to (1.1) one only needs Diophantine conditions

$$\left| \Omega - \sum_{i=1}^n k_i \omega_i \right| \geq \frac{\gamma}{|k|^\tau} \quad \forall_{k \in \mathbb{Z}^n \setminus \{0\}}$$

on all normal frequencies Ω (which should furthermore not vanish), the so-called first Mel'nikov condition, to exclude resonances (1.2). However, where the second Mel'nikov condition excluding resonances (1.3) is violated, the lower dimensional tori may cease to be normally elliptic; see section 3.3 for a more detailed discussion of the ensuing bifurcations. Under the Diophantine conditions (3.1) combining (1.1) and the two Mel'nikov conditions, one does obtain persistence of normally elliptic tori and their normal behaviour, provided that furthermore neither (1.2) nor (1.3) holds with $k = 0$ (see Broer *et al* (1996a), Rüssmann (2001) and references therein).

The remaining normal-internal resonances (1.2) are closely related to a vanishing normal frequency; in fact one may achieve $\Omega = 0$ by means of a coordinate change of the toral angles (see Broer *et al* (2003)). This case is studied in this paper, and we assume the degeneracy of the linear part of the Hamiltonian vector field to be as mild as possible, with a single vanishing Floquet exponent which furthermore has a nilpotent Jordan block $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$. To focus on this normal parabolicity, we discard additional hyperbolic and elliptic Floquet exponents and consider normally parabolic invariant n -tori in $n + 1$ degrees of freedom. The degeneracy of the linear part necessitates the inclusion of nonlinear terms. The degree, d , of the latter determines the co-dimension $d - 2$ and since n -tori form n -parameter families in a Hamiltonian system, parametrized by the actions conjugate to the toral angles, it is generic to encounter parabolic tori up to co-dimension n already if the Hamiltonian system does not depend on external parameters.

In the dissipative (general) context KAM theory is known to need external parameters for the persistence of quasi-periodic invariant tori. In particular, parameters are needed to keep

track of the frequencies of the torus while perturbing (see Moser (1967), Broer *et al* (1990) or Broer *et al* (1996a)). In Braaksma *et al* (1990), moreover, a systematic study was made of simple bifurcations of quasi-periodic tori, where the normal hyperbolicity is mildly violated. It turns out that persistent models exist in analogy to the standard bifurcation models of equilibria and closed orbits. In this analogy, certain continua in the parameter space have to be replaced by Cantor-like sets of large Hausdorff measure. Notably, this whole programme needs the assumption of reducibility of the normal linear part to a constant Floquet matrix by a change of variables. For a discussion, see section 7 of Broer *et al* (1990) and see Wagener (1998), Broer *et al* (1999), Broer and Wagener (2000), Takens and Wagener (2000) regarding a Hopf-like bifurcation of invariant tori where this assumption is not valid.

This paper aims to similarly treat a number of bifurcations in the Hamiltonian context, generalizing a first such result in Hanßmann (1998) to arbitrary (finite) co-dimension. The normal linear part of the bifurcating invariant tori is supposed to be parabolic, i.e. of the form $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$. We base our analysis on the techniques used in Hanßmann (1998) and You (1998). Let us briefly sketch the setting of the present problem.

We are interested in the behaviour near the bifurcating torus, whence we may choose the phase space to be $\mathbb{T}^n \times \mathbb{R}^n \times \mathbb{R}^2$, with coordinates $(x, y, (p, q))$ and symplectic form

$$\sigma = \sum_{i=1}^n dx_i \wedge dy_i + dq \wedge dp.$$

We are concerned with perturbations of a Hamiltonian system for which the torus $\mathbb{T}^n \times \{0\} \times \{0\}$ is invariant and the normal linear part has the (nilpotent) parabolic form

$$\begin{pmatrix} \dot{q} \\ \dot{p} \end{pmatrix} = \begin{pmatrix} 0 & a \\ 0 & 0 \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix}$$

for some $a \neq 0$. Mimicking the theory of bifurcations for equilibria and periodic solutions (cf Meyer (1970, 1975) or Broer *et al* (1993, 1995)), we add the following assumption. For some integer $d \geq 3$, the expansion of the unperturbed Hamiltonian in the (p, q) -direction has the principal part $(a/2)p^2 + (b/d!)q^d$, with $b \neq 0$. Moreover, we include parameters, first for the frequencies $\omega_1, \omega_2, \dots, \omega_n$ and second for the unfolding of the (cuspidal) singularity q^d , as dictated by singularity theory (cf Bröcker and Lander (1975)). Following Pöschel (1982) and Broer *et al* (1990), we localize in y and restrict to lowest order terms, concentrating on the situation around $y = 0$. In section 5 we come back to the ensuing possibility of letting y play the role of the parameters $\lambda \in \Lambda \subseteq \mathbb{R}^{d-2}$ and $\omega \in \mathcal{O} \subseteq \mathbb{R}^n$. For the moment disregarding these coordinate changes and re-parametrizations, we shall assume that the unperturbed family has the following ‘integrable’ form:

$$N(x, y, p, q; \lambda, \omega) = (\omega | y) + \frac{a(\omega)}{2} p^2 + \frac{b(\omega)}{d!} q^d + \sum_{j=1}^{d-2} \frac{\lambda_j}{j!} q^j, \quad (1.4)$$

where $(\cdot | \cdot)$ denotes the standard inner product on $\mathbb{R}^n$. This family first of all has a continuum of normally parabolic invariant tori

$$\mathbb{T}^n \times \{0\} \times \{0\} \times \{0\} \times \mathcal{O} \subseteq \mathbb{T}^n \times \mathbb{R}^n \times \mathbb{R}^2 \times \Lambda \times \mathcal{O},$$

i.e. for every frequency vector $\omega \in \mathcal{O}$ there is one such n -torus, given by the equations $y = 0, (p, q) = 0, \lambda = 0$. Next, for $\lambda \neq 0$ we find continuous branches of invariant tori of various types, normally hyperbolic, elliptic and parabolic, corresponding to the cuspidal hierarchy of singularity theory (cf Bröcker and Lander (1975), Arnol'd *et al* (1993)). Moreover, there are Lagrangian invariant $(n+1)$ -tori, foliating open pieces of the phase space. The general question of this paper is what remains of this global picture when we perturb to $H = N + P$,

Figure 1. Bifurcation diagram of N for $d = 4$. The phase portraits show the reduced one degree of freedom dynamics of (1.4) for the indicated values of (λ_1, λ_2) .

where P is an arbitrary perturbation, small in an appropriate sense. Throughout, for simplicity, we assume real analyticity of H in all variables and parameters, observing however that immediate adaptations exist for $H \in C^j$, for j sufficiently large, including $j = \infty$. See Pöschel (1982) or the appendix of Broer *et al* (1990).

This perturbation problem is not expected to have an affirmative answer for all parameters ω , but again only on a set of Cantor-like structure. Indeed, on the vector $\omega \in \mathcal{O}$ we impose the Diophantine conditions (1.1), where $\tau > n - 1$ is fixed and where $\gamma > 0$ is to be chosen later on. The first result of this paper roughly says the following. For values of ω in a Cantor set given by the above restriction, the family $H = N + P$, with P sufficiently small in an appropriate norm, again has such normally parabolic invariant n -tori near $y = 0$, $(p, q) = 0$, $\lambda = 0$. These perturbed tori, moreover, form a Whitney- C^∞ -family, implying that their union has a large Hausdorff measure. In the next section we shall give a precise formulation of the corresponding theorem. We remark that our conditions are global with respect to $\mathcal{O}$, i.e. not restricted to a small neighbourhood of some fixed frequency vector ω_0 satisfying (1.1).

The perturbed tori just mentioned are the most degenerate ones corresponding to the central singularity at $\lambda = 0$, and the remaining part of our perturbation problem asks what happens to the invariant tori of N that occur in the unfolding for $\lambda \neq 0$. In a second result we approach this problem recursively with respect to d . It turns out that the hierarchy of the cuspid families carries over to the KAM-setting.

Summarizing, we give a rough all-over description of the invariant tori found by this approach. The key already lies in the behaviour of the unperturbed integrable normal form. The smooth parametrizations of the various families of invariant tori found there will then be subject to Diophantine restrictions, meaning that the final result deals with a *Cantor stratification* in the product of phase space and parameter space.

The behaviour of the normal form, N , is best explained noting that the invariant tori give the product of phase space and parameter space the structure of a *ramified torus bundle*. An open and dense part is filled by the union of Lagrangian invariant $(n + 1)$ -tori, these define the regular fibres of this bundle. The complement consists of invariant n -tori, defining singular fibres of various degrees according to occurring bifurcations. In the space of external parameters λ and frequencies ω this yields a stratification—each stratum of co-dimension k parametrizing invariant n -tori that undergo a bifurcation of that same co-dimension.

To fix our thoughts let us concentrate on the case $d = 4$, see figure 1 for the bifurcation diagram of the lower dimensional tori defined by N . The point $\lambda_1 = \lambda_2 = 0$, where the two

lines $\{9\lambda_1^2 + 8\lambda_2^3 = 0\}$ meet, corresponds to the most degenerate parabolic torus. These lines stand for parabolic invariant tori that have some normal form like in (1.4), but with $d = 3$, i.e. N undergoes (*quasi-periodic*) *centre–saddle bifurcations* when these lines are crossed (cf Meyer (1970, 1975), Broer *et al* (1993, 1995), Hanßmann (1998)); this is related to a subordinate fold catastrophe. Concentrating on the ‘cusp’ case $a \cdot b > 0$, the values of λ with $9\lambda_1^2 > -8\lambda_2^3$ parametrize elliptic tori, while each λ with $9\lambda_1^2 < -8\lambda_2^3$ stands for two elliptic tori and a hyperbolic torus. In particular the system undergoes a (*quasi-periodic*) *Hamiltonian pitchfork bifurcation* under variation of λ_2 with $\lambda_1 \equiv 0$. When a and b have opposite signs, in the ‘dual cusp’ case, each λ with $9\lambda_1^2 < -8\lambda_2^3$ stands for one elliptic and two hyperbolic tori. This leads to a further bifurcation line $\{\lambda_1 = 0, \lambda_2 < 0\}$ where the two hyperbolic tori have the same energy, have coinciding stable and unstable manifolds and thus get connected by heteroclinic orbits. This *connection bifurcation* is an example of a global bifurcation subordinate to the local bifurcations defined by (1.4).

For the dynamics defined by N there is one bifurcation diagram for each frequency vector ω . Using a Kolmogorov-type non-degeneracy condition (cf (5.1) below), we may switch to the phase space where the actions y conjugate to the toral angles x play the role of the frequencies. In the product of phase space and parameter space the union of all lower dimensional tori is a stratified set of co-dimension 2, the complement of which is filled by $(n + d - 1)$ -parameter families of invariant $(n + 1)$ -tori. In this paper we show that, under a Hamiltonian perturbation, this stratification becomes a Cantor stratification, with all parametrizations getting restricted to Cantor sets defined by Diophantine conditions (while the actual invariant tori remain analytic tori).

Analysis of the type of bifurcation at hand most often takes place by means of a normalizing or averaging procedure. Indeed, in an integrable approximation we may detect the unperturbed dynamics by finding the most degenerate singularity and checking the parameter dependence. In the example of the quasi-periodic response problem, sketched below, this situation is clearly illustrated. Sometimes the actual number of parameters is less than the co-dimension of the singularity and we may have to resort to the path formalism. Compare this with the periodic case (Meyer 1970, 1975, Golubitsky and Schaeffer 1985, Golubitsky *et al* 1988).

2. Results

When proving a persistence theorem, the difficult part is to keep track of the most degenerate ‘object’ in the perturbed system. Our first step is therefore to look for the bifurcating normally parabolic invariant n -tori of X_H .

Let $\mathbb{T}^n$ be an n -torus and $\mathbb{Y} \subseteq \mathbb{R}^n$, $\mathbb{S} \subseteq \mathbb{R}^2$, $\Lambda \subseteq \mathbb{R}^{d-2}$ be neighbourhoods of the respective origins. By $\mathcal{O}_\gamma$ we denote the set of those frequency vectors $\omega \in \mathcal{O}$ that satisfy the Diophantine condition (1.1). We also need $\mathcal{O}'_\gamma := \{\omega \in \mathcal{O}_\gamma \mid d(\omega, \partial\mathcal{O}) \geq \gamma\}$. Furthermore $|\cdot|_A$ stands for the supremum norm on the set A .

Theorem 2.1. *Let the functions $a, b : \mathcal{O} \rightarrow \mathbb{R}$ in the normal form (1.4) satisfy $|a|_{\mathcal{O}}, |b|_{\mathcal{O}}, |1/a|_{\mathcal{O}}, |1/b|_{\mathcal{O}}, |Da|_{\mathcal{O}}, |Db|_{\mathcal{O}} < C$ for some constant $C > 0$. Then there exists a small positive constant ε , independent of $\mathcal{O}$, with the following property. For any analytic perturbation $H = N + P$ of (1.4) with*

$$|P|_{\mathbb{T}^n \times \mathbb{Y} \times \mathbb{S} \times \Lambda \times \mathcal{O}} < \varepsilon$$

there exists a C^∞ -diffeomorphism Φ on $\mathbb{T}^n \times \mathbb{R}^n \times \mathbb{R}^2 \times \mathbb{R}^{d-2} \times \mathcal{O}$ such that

- (1) Φ is real analytic for fixed ω .
- (2) Φ is symplectic for fixed (λ, ω) .

- (3) Φ is C^∞ -close to the identity.
- (4) On $\mathbb{T}^n \times \mathbb{R}^n \times \mathbb{R}^2 \times \mathbb{R}^{d-2} \times \mathcal{O}'_\gamma \cap \Phi^{-1}(\mathbb{T}^n \times \mathbb{Y} \times \mathbb{S} \times \Lambda \times \mathcal{O})$ one can split $H \circ \Phi = N_\infty + P_\infty$ into an integrable part N_∞ and higher order terms P_∞ . Here N_∞ has the same form as N , see (1.4). The x -dependence is pushed into the higher order terms, i.e. $\partial^{|l|+i+j+h} P_\infty / \partial y^l \partial p^i \partial q^j \partial \lambda^h(x, 0, 0, 0, 0, \omega) = 0$ for all $(x, \omega) \in \mathbb{T}^n \times \mathcal{O}'_\gamma$ and all l, i, j, h satisfying $2d|l| + di + 2j + (2d - 2)h_1 + \dots + 4h_{d-2} \leq 2d$.

We prove this theorem in section 6, using a KAM iteration scheme. But let us first elaborate its implications.

An immediate consequence is the existence of normally parabolic n -tori at the ‘origin’ $y = p = q = \lambda = 0$. These are parametrized by the Diophantine frequency vectors $\omega \in \mathcal{O}'_\gamma$, i.e. they form a *Cantor family*. The set $\mathcal{O}'_\gamma$ has locally the product structure $\mathbb{R} \times \text{Cantor dust}$. We colloquially refer to such sets as Cantor sets and reserve the name Cantor dust to those Cantor sets that are indeed totally discontinuous. At $\lambda = 0$ the Cantor family corresponds to the most degenerate normally parabolic tori. We claim that the whole bifurcation scenario of the integrable family N persists under the perturbation by P on Cantor sets. For a precise formulation we need the concept of a Cantor stratification.

Recall that a subset $S \subseteq M$ of a C^∞ -manifold is said to be stratified into finitely many locally closed C^∞ -submanifolds (called ‘strata’) $S_k \subseteq M$, $k = 0, \dots, m$ if $S = \bigcup S_k$ and the topological boundary $\partial S_k \subseteq S$ lies in the union $\bigcup_{l > k} S_l$ for all $k = 0, \dots, m$. Thus, S_0 is open in S and the complement $S \setminus S_0$ is stratified into $S_1, \dots, S_m$. It is convenient to choose $m = \dim M$, giving S_k the co-dimension k (within M).

The polynomial normal forms from singularity and catastrophe theory all have semi-algebraic catastrophe and bifurcation sets. This gives the simplest examples of stratified sets. The further complications in the definition of such stratifications largely arise from the fact that singularity theory allows analytic or smooth transformations and re-parametrizations, that need not be algebraic. The ensuing problem is to characterize the analytic or smooth stratifications thus obtained (cf Whitney (1965) or Pflaum (2001)). Semi-algebraic stratifications (and those obtained by smooth transformations) satisfy Whitney’s conditions (A) and (B) imposing restrictions on the behaviour of the limit tangent spaces when approaching a boundary stratum (cf Pflaum (2001) and references therein). Therefore we restrict ourselves from now on to such *Whitney stratifications*.

Definition 2.2. A collection C_k , $k = 0, \dots, m$ of Cantor sets of (Hausdorff)-dimension $m-k$ is called a *Cantor stratification* (of $C = \bigcup C_k$) if there are $(m-k)$ -dimensional manifolds $S_k \supseteq C_k$ that make $\bigcup S_k$ a Whitney stratification.

Thus, we just extend the above class of smooth transformations a bit further and allow for Whitney- C^∞ -smooth transformations with respect to the union Cantor set C . The corresponding Whitney extensions also are smooth on the whole semi-algebraic set, which brings us to the above setting. Our Cantor sets C_k are defined by Diophantine conditions (1.1), and it turns out that the continuous factors $\mathbb{R}^{d-1}$ in $\Lambda \times \mathcal{O}'_\gamma$ are transversal to the singular strata of the semi-algebraic stratification defined by singularity theory. For more details see section 5.1 and Broer *et al* (2005a).

We use theorem 2.1 to obtain a Cantor stratification in an inductive manner. Near the above Cantor family of most degenerate parabolic tori we expect bifurcating tori of lower co-dimensions to occur—in exactly the same way as the normal form has a bifurcation set that is stratified into the various subordinate bifurcations. Thus, we invoke theorem 2.1 using a normal form like (1.4) with d replaced by $d - 1$, then by $d - 2$ and so on until we reach the subordinate quasi-periodic centre–saddle bifurcations. Here we use the cuspidal hierarchy

of singularities of type A_k (cf Bröcker and Lander (1975), Arnol'd *et al* (1993)). In section 4 this is used to prove the following result.

Theorem 2.3. *Under the conditions of theorem 2.1, there is a Cantor stratification of a Cantor subset of $\Lambda \times \mathcal{O}$ of large measure into $(n + d - k - 2)$ -dimensional Cantor sets C_k , $k = 0, \dots, d - 2$, such that C_0 parametrizes Cantor families of elliptic and hyperbolic tori and C_k , $k = 1, \dots, d - 2$ parametrize Cantor families of parabolic tori of co-dimension k .*

Remark 2.4. As the proof in section 4 shows, it is the stratification of Λ as dictated by singularity theory that gets ‘Cantorized’. In particular, we get a Cantor family $\{\lambda\} \times \mathcal{O}'_\gamma$ of normally parabolic tori for each $\lambda \in \Lambda_d$ in the catastrophe set Λ_d of N_∞ , the set of parameters for which the one-dimensional potential

$$V_\infty^\lambda(q) = \frac{b_\infty(\omega)}{d!} q^d + \sum_{j=1}^{d-2} \frac{\lambda_j}{j!} q^j$$

has a degenerate critical point. The open and dense complement $\Lambda_0 = \Lambda \setminus \Lambda_d$ gives rise to normally hyperbolic and elliptic tori, corresponding to the non-degenerate critical points of V_∞^λ . While the former are, for fixed $\lambda \in \Lambda_0$, still parametrized by the Cantor set $\mathcal{O}'_\gamma$ of Diophantine frequency vectors, the normally elliptic tori are, for fixed $\lambda \in \Lambda_0$, parametrized by a Cantor subset of $\mathcal{O}'_\gamma$ since additional normal-internal resonances have to be avoided, see section 5.2. When d is even, the potential V_∞^λ has for each $\lambda \in \Lambda$ at least one critical point, and in the case $ab < 0$ we obtain hyperbolic-type tori. This yields a family of invariant n -tori parametrized by a Cantor set of large n -dimensional (Hausdorff)-measure that is defined by the Diophantine condition (1.1). Hence, we recover the result of You (1998).

Remark 2.5. The normal form (1.4) has many homoclinic orbits to hyperbolic n -tori, where stable and unstable manifolds coincide. In the present Hamiltonian context homoclinic orbits are a typical phenomenon. However, one expects the stable and unstable manifolds to split. For a generic perturbation P this leads to transversal homoclinic orbits. When the system depends on parameters, homo- and heteroclinic bifurcations are also involved. The angle between the stable manifold and the unstable manifold, at such a transversal homoclinic orbit, is expected to be exponentially small. Subordinate to a ‘primary’ homoclinic orbit, variation of the parameters λ may lead to homoclinic bifurcations, involving tangencies between the stable and unstable manifolds (cf Kan *et al* (1992), Palis and Takens (1993)). Similar observations apply *mutatis mutandi* to homoclinic orbits of parabolic n -tori.

Remark 2.6. Whenever two unstable n -tori have the same energy they may be connected by heteroclinic orbits. Let us again concentrate on the case of hyperbolic tori, though almost no modifications are needed if one or both tori are parabolic. For the integrable normal form there is a set of co-dimension 1 in parameter space for which connection bifurcations occur. Under variation of a further, transversal, parameter, the energy difference of the two hyperbolic tori changes from a positive to a negative value. A model Hamiltonian on $\mathbb{T}^n \times \mathbb{R}^n \times \mathbb{R}^2$ is given by

$$K(x, y, p, q) = h(y) + \frac{1}{2}p^2 + \frac{1}{2}q^2 - \frac{1}{24}q^4 - y_1 q. \quad (2.1)$$

The circumstances of the formation of heteroclinic orbits change drastically under perturbation. In the generic case the stable and unstable manifolds that coincide for the unperturbed system have transversal intersections, which, however, are expected to be exponentially small. As a result the region in parameter space where heteroclinic orbits exist becomes a (exponentially small) ‘horn’ (cf Broer *et al* (1996b), Broer and Roussarie (2001)). In the dual cusp case, for instance, this leads to a bifurcation diagram as sketched in figure 2(a). The boundary lines of

Figure 2. (a) In the dual cusp case the connection bifurcation at $\{\lambda_1 = 0, \lambda_2 < 0\}$ perturbs to an (exponentially small) open region where heteroclinic orbits occur. (b) A ‘first’ tangency bifurcation of heteroclinic orbits. (Courtesy of Carles Simó.)

the horn stand for ‘first’ heteroclinic tangencies, as depicted in figure 2(b). Within the horn, secondary heteroclinic tangencies are *abundant*.

To speak of heteroclinic orbits the α - and ω -limit sets, the hyperbolic tori, have to persist. As this happens on Cantor sets of large measure, their intersection is again a large Cantor set (and in particular non-empty). It should be instructive to experiment with concrete perturbations of, e.g., (2.1).

Remark 2.7. In applications the Hamiltonian is often invariant under some compact symmetry group. This strongly influences the bifurcations occurring in that the co-dimension within the corresponding ‘symmetric universe’ is typically much lower. Correspondingly, one can use equivariant singularity theory (see Poënar (1976)) to derive adapted unfoldings. As the proof of theorem 2.1 is of Lie algebra type and hence structure-preserving (cf Moser (1967), Broer *et al* (1996a)), the result carries over.

On the other hand, every symmetry raises the question: what happens if this symmetry is broken, how does the symmetric system unfold within the space of all systems? Here the concept of *distinguished parameters* comes into play (see Golubitsky and Schaeffer (1985), Broer *et al* (1993, 1995)). Within a ‘complete’ unfolding like (1.4), those parameters ‘ μ ’ that are also present in a symmetric unfolding are distinguished with respect to the parameters ‘ v ’ that break the symmetry in that only re-parametrizations of the form $(\mu, v) \mapsto (\tilde{\mu}(\mu, v), \tilde{v}(v))$ with $\tilde{v}(0) = 0$ are admitted to ensure that the new $\tilde{\mu}$ can still be interpreted as ‘symmetry parameters’ while the new $\tilde{v}$ again break the symmetry.

Remark 2.8. An important case is if the Hamiltonian is invariant under an involution, e.g. $R : (x, y, p, q) \mapsto (x, -y, -p, q)$. Then R maps phase curves to phase curves, reversing the time, and the system is called *reversible* (cf Sevryuk (1986), Broer and Huitema (1995)). For instance, the normal form (1.4) is reversible with respect to $(x, y, p, q) \mapsto (-x, y, -p, q)$.

The involution $(x, y, p, q) \mapsto (-x, y, p, -q)$ allows us to reduce the parameters in the unfolding (1.4), with even d , by half. In this way, e.g., the cusp case ($d = 4$) leads to the (quasi-periodic) Hamiltonian pitchfork bifurcation ($\lambda_1 \equiv 0$).

Let $\mathbb{T}^n \times \{0\} \times \{0\}$ be an invariant torus of a Hamiltonian system on $\mathbb{T}^n \times \mathbb{R}^n \times \mathbb{R}^2$ with normal ‘linearization’ $\frac{1}{2}p^2$. Then any x -independent (whence integrable) perturbation that is invariant under $q \mapsto -q$ leads to an invariant torus close to the origin, and also non-integrable perturbations that are reversible with respect to $(x, y, p, q) \mapsto (-x, y, p, -q)$ lead to invariant

tori parametrized by pertinent Cantor sets (see You (1999)). Naturally, the normal behaviour of such tori cannot be controlled and depends on the perturbation at hand.

Remark 2.9. A 1-parameter family of periodic orbits that encounters the Floquet multiplier -1 (generically) undergoes a period-doubling bifurcation. Similarly, we expect a frequency-halving bifurcation of invariant tori when one of the normal frequencies enters the lattice

$$\{\pi i + 2\pi i(\omega \mid k) \mid k \in \mathbb{Z}^n\}$$

defined by the (internal) frequency vector ω . Passing to a 2-fold covering space (cf Braaksma *et al* (1990), Broer and Vegter (1992), Ferrer *et al* (2002), Broer *et al* (2003)), we obtain a lifted system that is invariant under the π -rotation $(x, y, p, q) \mapsto (x, y, -p, -q)$. Here the normal frequency of the bifurcating torus becomes zero, i.e. the normal linear part is either $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ or $\begin{pmatrix} 0 & a \\ 0 & 0 \end{pmatrix}$ with $a \neq 0$. For the latter normally parabolic case we indicate at the end of the next section what our results imply for such frequency-halving bifurcations.

3. Applications

As soon as dynamical systems depend on (external) parameters, bifurcations become a general phenomenon. In the present case of Hamiltonian systems the action variables $y_1, \dots, y_n$ conjugate to the toral angles on $\mathbb{T}^n$ play the role of internal or distinguished parameters, and we come back to the resulting possibility of parameter reduction in section 5 below. In the dissipative setting there are no ‘conjugate’ phase space variables that may act as parameters and one always needs a dependence of the system on external parameters for bifurcations to occur.

A quasi-periodic bifurcation usually involves Cantor stratifications in the product of phase space and parameter space, where the continuous counterpart is a familiar stratification to be retrieved in the bifurcation sets of integrable approximations. The ‘Cantorification’ strongly depends on a dense set of resonances. Indeed, these resonances form the skeleton of the gap structure of the Cantor stratification. The gaps contain the resonant and chaotic dynamics, amidst which the Cantor stratification is a quasi-periodic, orderly part of the dynamics.

Therefore, the occurrence of quasi-periodic bifurcations needs at least three phase space variables and two parameters in the dissipative context and at least three degrees of freedom in the present Hamiltonian case. However, although this phenomenon is already present in quite low dimensional systems, its presence in higher dimensional dynamics seems even more prominent. Indeed, in (weakly) coupled systems, resonances are hard to avoid and the same holds for systems with periodic or quasi-periodic forcing. In many of these cases a smooth normal form truncation gives a stratified bifurcation set, that is Cantorized upon re-entering the remainder terms.

Below we illustrate our results with applications to perturbations of the Euler top and forced oscillators and treat the normally parabolic frequency-halving bifurcations. Furthermore we show in Broer *et al* (2005b) how these phenomena organize the destruction of resonant Lagrangian tori. Globally speaking, one cannot hope to get insight into the dynamics of larger systems without understanding how smooth bifurcational structures are Cantorized by resonances and KAM theory. For examples concerning other quasi-periodic Hamiltonian bifurcations we refer to de Jong (1999) and Broer *et al* (2004b, 2004c). Completely new phenomena arise where a lower dimensional torus undergoing, e.g., a quasi-periodic Hamiltonian pitchfork bifurcation becomes internally resonant (see Litvak-Hinzenzon and Rom-Kedar (2002a, 2002b)). For quasi-periodic bifurcations in the dissipative and reversible settings see Braaksma and Broer (1987), Braaksma *et al* (1990), Broer and Huitema (1995), Broer *et al* (2004d) and references therein.

3.1. Perturbations of the Euler top

The *free rigid body* is a Hamiltonian system that describes the motion of a rigid (i.e. non-deformable) body in the absence of external forces or torques. To concentrate on the rotational aspect of the motion one fixes the body at one point (not necessarily the centre of mass) and obtains a Hamiltonian system with three degrees of freedom (cf Arnol'd (1978)). We speak of an Euler top if the body is in addition *dynamically symmetric*, i.e. two moments of inertia are equal.

The Euler top is not only integrable, but even superintegrable, as the energy and the three components of the angular momentum define four independent integrals of motion. We stress that this is true for the more general free rigid body with a fixed point as well. However, the rotational–precessional motion along the invariant 2-tori is particularly transparent in the dynamically symmetric case of the Euler top, where it consists of a pure rotation about its *figure axis*, superposed by a pure precession of the figure axis about the (fixed) direction of the angular momentum.

While the superintegrability simplifies the analysis of the unperturbed motion, the perturbation analysis becomes more involved. The perturbation we have in mind is given by an external force field. For fast motions the kinetic energy of a rigid body is large with respect to the potential energy, and the system may be treated as a perturbation of the Euler top (cf Benettin and Fassò (1996)). We stress again that there is no conceptual difference between the Euler top and the general free rigid body with a fixed point—the body is not assumed to be symmetric with respect to the figure axis, whence the perturbation analysis takes place in three degrees of freedom.

The 4-parameter family of invariant 2-tori in the unperturbed Euler top system is not structurally stable even with respect to integrable perturbations. In fact, for the Lagrange top itself the torque exerted by the perturbing force field causes the angular momentum to move, leading to 3-parameter families of invariant 3-tori (cf Arnol'd (1978)). Consequently, only two-dimensional Cantor subfamilies of this 4-parameter family of invariant 2-tori are expected to survive a perturbation, and it is also the perturbation itself that gives rise to the bifurcation scenario (cf Hanßmann (1995)).

In Hanßmann (1996) a perturbation by a $\mathbb{Z}_2 \times \mathbb{Z}_2$ symmetric conservative force field is studied. A normal form approach yields a formal 2-torus symmetry, giving rise to an integrable approximation. The 2-torus symmetry of the normal form allows us to reduce to a one degree of freedom problem, which is found to display Hamiltonian pitchfork bifurcations.

The normal form by itself is a perturbation of the Euler top, and the occurring invariant 2-tori may be thought of as surviving this perturbation: the motion (still) consists of a rotation about the figure axis, superposed by a precession of the figure axis about the (fixed) direction of the angular momentum. For the majority of initial conditions the perturbation will cause the angular momentum to move, leading to invariant 3-tori of the integrable normal form (cf Hanßmann (1996)). It is in fact generic for external force fields to have normal forms with 3-parameter families of invariant 3-tori, cf Mazzocco (1997), where it is also shown that three-dimensional Cantor families of invariant 3-tori persist the perturbation from the normal form to the original system.

Now the frequency ratio of the invariant 2-tori involved in the Hamiltonian pitchfork bifurcations is determined by the ratio of the actions conjugate to the toral angles, and this same ratio plays the role of the bifurcation parameter. Thus, the two distinguished parameters are not sufficient to ensure persistence, and the whole bifurcation scenario might fall into a resonance gap. To overcome this ‘lack of parameter’ problem, one can consider the inertia tensor as an external parameter, leading to persistence of the quasi-periodic Hamiltonian pitchfork

bifurcation for ‘most’ rigid bodies. For a similar treatment of the quasi-periodic centre–saddle bifurcation occurring for ‘generic’ *affine force fields* (without $\mathbb{Z}_2 \times \mathbb{Z}_2$ symmetry), see Hanßmann (1998).

In fact, one may also consider the coefficients of the external force field as parameters. Within the class of affine force fields

$$G = -\alpha e_x - \beta e_y - \gamma e_z - a x e_x - b y e_y - c z e_z,$$

one can use non-zero values of α and γ to break the discrete symmetry. In this way one obtains the whole ‘cusp’ scenario of (1.4) with $d = 4$ (cf Nelk (1998)).

As it is the perturbation itself that gives rise to the bifurcation scenario, the coefficient functions a and b in (1.4) are of the order δ of that perturbation (while the perturbing terms of order δ^2 have to be computed through a first normalizing transformation). We point out in section 6.3 that not only does theorem 2.1 apply to such systems with two time scales, but the results obtained are in fact even better in this context.

3.2. Applications of the unfolding theory in the response context

One slightly theoretical class of examples is motivated by the oscillator with quasi-periodic forcing

$$\ddot{q} = -V'_\lambda(q) + \varepsilon f(t)$$

with $f(t) = F(t\omega_1, \dots, t\omega_n)$, for an analytic function $F : \mathbb{T}^n \rightarrow \mathbb{R}$. Here we take the frequency vector $\omega = (\omega_1, \dots, \omega_n)$ non-resonant or even Diophantine. The family $V = V_\lambda(q)$ of potentials is one of the cuspidal unfoldings described earlier. In this context we may fix ω and only use λ as a multi-parameter. The general aim is to study the possible dynamics near response solutions, quasi-periodic with the same frequency vector, ω (see Stoker (1950), Moser (1965), Broer *et al* (1996a) and the bibliography of the latter reference). First we re-write the equation in vector field form,

$$\begin{aligned}\dot{x} &= \omega, \\ \dot{q} &= p, \\ \dot{p} &= -V'_\lambda(q) + \varepsilon F(x)\end{aligned}$$

with phase space $\mathbb{T}^n \times \mathbb{R}^2$. The problem now concerns the dynamical behaviour, in particular quasi-periodic bifurcations of invariant tori close to $\mathbb{T}^n \times \{0\}$. Although these vector fields are volume preserving, they are not necessarily Hamiltonian. To establish the latter property, we modify them to

$$\begin{aligned}\dot{x} &= \omega, \\ \dot{y} &= \varepsilon q \nabla F(x), \\ \dot{q} &= p, \\ \dot{p} &= -V'_\lambda(q) + \varepsilon F(x),\end{aligned}$$

which is a Hamiltonian family of vector fields $X = X_\lambda(x, y, p, q)$ on $\mathbb{T}^n \times \mathbb{R}^n \times \mathbb{R}^2$, with corresponding Hamiltonian functions $H_\lambda(x, y, p, q) = \frac{1}{2}p^2 + (\omega \mid y) + V_\lambda(q) - \varepsilon q F(x)$. This system clearly fits in our context. To see this, consider the family of potentials given by

$$V_\lambda(q) = q^d + \sum_{j=1}^{d-2} \lambda_j q^j.$$

Indeed, theorems 2.1 and 2.3 directly apply to the corresponding systems. For $d = 3$ a quasi-periodic centre–saddle bifurcation occurs, corresponding to a simple fold singularity in the

1-parameter family V_λ . This quasi-periodic bifurcation of the invariant tori has an obvious translation to the corresponding families of ω -quasi-periodic response solutions (see also Broer *et al* (2003))—similarly for the cusp ($d = 4$) and the higher cuspoids. As follows from the above theorems, the smooth stratifications for the families of V_λ functions fall apart into Cantor stratifications by the perturbation.

Remark 3.1. The general proof in section 6 below can be easily adapted to this response context, by choosing all conjugacies in such a way that they leave x fixed.

Remark 3.2. Compare with the periodic case, where the forcing effects a far milder complication of the unperturbed, smooth stratification. Indeed, in the periodic case only finitely many (strong) resonances have to be excluded, as they would give rise to interruptions of the smooth stratification.

Remark 3.3. Symmetry properties like reversibility are optional in this set-up. For example, consider the involution $R : (x, y, p, q) \mapsto (-x, y, p, -q)$ and the vector field satisfying $R_*(X) = -X$. This requires that $F(-x) = -F(x)$ and $V_\lambda(-q) = V_\lambda(q)$, with ensuing obvious modifications in the normal forms from equivariant singularity theory.

3.3. The frequency-halving bifurcation

Like maximal tori of a Hamiltonian system, normally hyperbolic invariant tori persist under small perturbations, provided that the Diophantine conditions (1.1) on the internal frequency vector $\omega = (\omega_1, \dots, \omega_n)$ are met. For normally elliptic tori the necessary Diophantine conditions involve the normal frequencies $\Omega_1, \dots, \Omega_m$ and read

$$|k_1\omega_1 + \dots + k_n\omega_n + \ell_1\Omega_1 + \dots + \ell_m\Omega_m| \geq \frac{\gamma}{|k|^\tau}, \quad \forall_{k \in \mathbb{Z}^n \setminus \{0\}} \quad \forall_{\ell \in \mathbb{Z}^m, |\ell| \leq 2}, \quad (3.1)$$

where $\tau > n - 1$ is again fixed and $\gamma > 0$. While the conditions with $\ell = 0$ merely re-phrase (1.1), the four types of extra conditions exclude possible bifurcations.

For two coefficients of ℓ to be non-zero we need at least two normal degrees of freedom. The violation

$$\Omega_1 + \Omega_2 = \sum_{i=1}^n k_i \omega_i$$

of (3.1) is related to a (quasi-periodic) Hamiltonian Hopf bifurcation (cf Broer *et al* (2004a, 2004c)). On the other hand, tori with

$$\Omega_1 - \Omega_2 = \sum_{i=1}^n k_i \omega_i$$

persist and do not bifurcate (see de Jong (1999), Broer *et al* (2004a)). In both cases the condition on the normal frequencies is equivalent to

$$\Omega_1 = \pm \Omega_2$$

by a symplectic change of variables (see Xu and You (2001)). The remaining two cases only require one normal degree of freedom. The resonance (1.2) leads to

$$\Omega = 0$$

after a better choice of the toral angles (cf Broer *et al* (2003)). Then either the normal linear part is $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ (cf Broer *et al* (2004b)), or the bifurcating torus is normally parabolic, in which case our theory applies. The last possibility to violate (3.1) is

$$2\Omega = \sum_{i=1}^n k_i \omega_i$$

with at least one of the k_i odd. Here we pass to a 2-fold covering space to recover (1.2) (cf Braaksma *et al* (1990), Broer *et al* (2003)). Again there are two cases. We concentrate on the normally parabolic case as the other case (in which the normal linear part vanishes completely) lies outside the scope of this paper, but see Hanßmann (2004) for the simplest quasi-periodic bifurcation with normal linear part $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ on the 2-fold covering space.

The lifted system on the covering space is invariant under the π -rotation $(p, q) \mapsto (-p, -q)$. When passing to the integrable normal form N , we acquire an additional reflectional symmetry $(p, q) \mapsto (-p, q)$ since p enters (1.4) only as p^2 . While this symmetry usually has no consequences, in combination with the above π -rotation it now leads to a second reflectional symmetry $(p, q) \mapsto (p, -q)$ whence q only enters squared in (1.4) as well. Thus d is even in the principal part $(a/2)p^2 + (b/d!)q^d$ of N , and the unfolding terms are even powers of q as well, i.e. the normal form reads

$$N(x, y, p, q; \lambda, \omega) = (\omega \mid y) + \frac{a(\omega)}{2} p^2 + \frac{b(\omega)}{d!} q^d + \sum_{j=1}^{d/2-1} \frac{\lambda_j}{j!} q^{2j}. \quad (3.2)$$

This ensures in particular that $(p, q) = (0, 0)$ consists of invariant n -tori, as dictated by the system being a 2:1 lift.

The whole perturbation analysis may now be carried out on the covering space. Indeed, the general proof in section 6 below can as well be carried out with all mappings equivariant with respect to the π -rotation $(p, q) \mapsto (-p, -q)$.

The implications for the bifurcation scenario of the invariant tori are easily obtained from the equivariant form (3.2) of N . For instance, when $d = 4$ we obtain the usual ‘period-doubling’ scenario. Thus, for $a \cdot b > 0$, the invariant torus $(p, q) = (0, 0)$ turns from normally elliptic to normally hyperbolic as λ_1 passes through 0 (recall that λ_1 is here the coefficient of q^2), and a normally elliptic invariant torus with one frequency halved detaches. In the dual cusp case $a \cdot b < 0$ the detaching torus with one frequency halved is normally hyperbolic and the invariant torus $(p, q) = (0, 0)$ turns from normally hyperbolic to normally elliptic. See also Broer *et al* (2003).

4. Proof of theorem 2.3

Let us first consider the integrable Hamiltonian system with Hamiltonian function (1.4). The quasi-periodic flow induced by the term $(\omega \mid y)$ is superposed by the one degree of freedom system with Hamiltonian

$$\frac{a(\omega)}{2} p^2 + \frac{b(\omega)}{d!} q^d + \sum_{j=1}^{d-2} \frac{\lambda_j}{j!} q^j.$$

We have already seen in section 3.2 that the latter is an oscillatory system describing the motion of a one-dimensional particle in the potential

$$V_d(q, \lambda) := \frac{b(\omega)}{d!} q^d + \sum_{j=1}^{d-2} \frac{\lambda_j}{j!} q^j. \quad (4.1)$$

Applying singularity theory to V_d , one obtains the cuspidal hierarchy of singularities of type A_{k+1} , $k = 0, \dots, d-2$ (cf Bröcker and Lander (1975), Arnol'd *et al* (1993)). In our context this means that the parameter space Λ is stratified according to the degeneracy of the occurring parabolic tori (the singularities of type A_1 in the open stratum $S_0 \subseteq \Lambda$ correspond to elliptic and hyperbolic tori).

This allows us to lead the situation around some higher stratum S_k back to theorem 2.1. For completeness' sake the necessary computations are re-done here. With (4.1) the normal form (1.4) reads

$$N = (\omega \mid y) + \frac{a(\omega)}{2} p^2 + V_d(q, \lambda)$$

and by a translation $(Y, P, Q) = (y, p, q - c)$ transforms into

$$N = (\omega \mid Y) + \frac{a(\omega)}{2} P^2 + \frac{b(\omega)}{d!} Q^d + \frac{cb(\omega)}{(d-1)!} Q^{d-1} + \sum_{j=1}^{d-2} \frac{V_d^{(j)}(c, \lambda)}{j!} Q^j, \quad (4.2)$$

where we dropped the constant term $V_d(c, \lambda)$. Here $c = c(\lambda_{k+1}, \lambda_{k+2}, \dots, \lambda_{d-2})$ only depends on the last $d-k-2$ parameters (for some k to be chosen) and $V_d^{(j)}$ denotes the j th derivative of V_d with respect to q . The idea is to choose c on the stratum of parabolic tori of co-dimension k , which can be parametrized by the last $d-k-2$ parameters.

Let us illustrate the situation in the cusp case, $d = 4$, $k = 1$, for definiteness with positive a and b . Choosing $c := \pm \sqrt{-2\lambda_2/b(\omega)}$, equation (4.2) reads

$$N = (\omega \mid Y) + \frac{a(\omega)}{2} P^2 + \frac{b(\omega)}{24} Q^4 \pm \sqrt{\frac{-2\lambda_2}{b(\omega)}} \frac{b(\omega)}{6} Q^3 + \left(\lambda_1 \pm \frac{2\lambda_2}{3} \sqrt{\frac{-2\lambda_2}{b(\omega)}} \right) Q.$$

Fixing $\lambda_2 = -\hat{\lambda}_2 > 0$ and varying λ_1 around $\hat{\lambda}_1 := \pm \frac{2}{3} \hat{\lambda}_2 \sqrt{+2\hat{\lambda}_2/b(\omega)}$, we get an unfolding of the parabolic torus at $(p, q, \lambda) = (0, c, \hat{\lambda}_1, -\hat{\lambda}_2)$. Let us make this explicit, writing

$$\Lambda_1 := \lambda_1 - \hat{\lambda}_1.$$

To apply theorem 2.1 we have to show that the additional term $\frac{1}{24}b(\omega)Q^4$ may be treated as a perturbation. This can be achieved by a scaling

$$(y, p, q, \lambda_1, \Omega) = \left(\hat{\lambda}_2^{-11/4} Y, \hat{\lambda}_2^{-7/4} P, \hat{\lambda}_2^{-1} Q, \hat{\lambda}_2^{-5/2} \Lambda_1, \hat{\lambda}_2^{-3/4} \omega \right)$$

and then dividing N by $\hat{\lambda}_2^{7/2}$. Note that this scaling amounts to re-scaling time by $\hat{\lambda}_2^{3/4}$ and to a global multiplication of the symplectic structure by $\hat{\lambda}_2^{-11/4}$. Indeed, we cannot scale $x \in \mathbb{T}^n$ and therefore had also to re-scale the frequency; even if ω varies in a compact domain the 'new' Ω grows unboundedly for $\hat{\lambda}_2 \rightarrow 0$. This is the reason why we formulate our theorems for possibly unbounded frequency domains $\mathcal{O}$.

We have now transformed N into the normal form of the quasi-periodic centre–saddle bifurcation, perturbed by $\sqrt{\hat{\lambda}_2} \frac{1}{24} b(\omega) q^4$ —which becomes arbitrarily small for $\hat{\lambda}_2 \rightarrow 0$, i.e. the closer we get to the central bifurcation at $(\lambda_1, \lambda_2) = (0, 0)$. In fact, figure 1 also lies at the basis of the stratification to subordinate bifurcations for general d as the parabolic tori involved in subordinate bifurcations of co-dimension $d-1$ occur at points $(0, c, \hat{\lambda}) \neq (0, 0, 0)$ satisfying

$$V_d'(c, \hat{\lambda}) = V_d''(c, \hat{\lambda}) = \dots = V_d^{(d-3)}(c, \hat{\lambda}) = 0,$$

whence $c = \pm \sqrt{-2\hat{\lambda}_{d-2}/b(\omega)}$ and recursively

$$\hat{\lambda}_j = -\frac{b(\omega)}{(d-j)!}c^{d-j} - \frac{\hat{\lambda}_{d-2}}{(d-j-2)!}c^{d-j-2} - \dots - \hat{\lambda}_{j+1}c, \quad j = 1, \dots, d-3.$$

The projection to the $(\lambda_{d-3}, \lambda_{d-2})$ -space again is the cusp.

For general $k < d-2$, the values $\hat{\lambda}_1, \dots, \hat{\lambda}_k$ and c are determined according to

$$V'_d(c, \hat{\lambda}) = V''_d(c, \hat{\lambda}) = \dots = V_d^{(k+1)}(c, \hat{\lambda}) = 0 \neq V_d^{(k+2)}(c, \hat{\lambda}).$$

Fixing the last $d-k-2$ parameters and varying the first k around $(\hat{\lambda}_1, \dots, \hat{\lambda}_k)$ as thus obtained, we get an unfolding of the parabolic torus at $(p, q, \lambda) = (0, c, \hat{\lambda})$. Let us again write explicitly

$$\Lambda_j := \lambda_j - \hat{\lambda}_j, \quad j = 1, \dots, k.$$

To apply theorem 2.1 we scale with respect to $\delta := |V_d^{(k+2)}(c, \hat{\lambda})|$. Note that in the cusp case $d = 4, k = 1$ this amounts to $\delta = \sqrt{\hat{\lambda}_2}$. While this quantity ‘directly’ only depends on $\hat{\lambda}_{k+2}, \hat{\lambda}_{k+3}, \dots, \hat{\lambda}_{d-2}$, it also depends on $\hat{\lambda}_{k+1}$ through $c = c(\hat{\lambda}_{k+1}, \dots, \hat{\lambda}_{d-2})$; and it is in particular possible to let $\delta \rightarrow 0$ by letting $\hat{\lambda}$ tend to the stratum of co-dimension $k+1$, changing only $\hat{\lambda}_{k+1}$. Then the scaling

$$\begin{aligned} y &= \delta^{-k-9/2} Y, \\ p &= \delta^{-k-5/2} P, \\ q &= \delta^{-2} Q, \\ \lambda_1 &= \delta^{-2k-3} \Lambda_1, \\ \lambda_2 &= \delta^{-2k-1} \Lambda_2, \\ &\vdots \\ \lambda_k &= \delta^{-5} \Lambda_k, \\ \Omega &= \delta^{-k-1/2} \omega, \\ T &= \delta^{k+1/2} t, \end{aligned}$$

together with a division of N by δ^{2k+5} , allows us to factor a common δ from the higher order terms and thus treat these as a perturbation.

5. Reduction of parameters

The normal form (1.4) depends on the parameters $\omega_i, i = 1, \dots, n$ and $\lambda_j, j = 1, \dots, d-2$. Below we discuss why this seemingly special situation is in fact very general. Then we show how the (Cantor)-strata of lower dimensions fit within the (Cantor)-strata of higher dimensions.

5.1. Replacing parameters by phase space variables

Given a (single) Hamiltonian system with (unperturbed) Hamiltonian function H_0 , the Kolmogorov-type non-degeneracy condition

$$\det(D_y^2 H_0) \neq 0 \tag{5.1}$$

enforces the frequency mapping $y \mapsto \omega(y) := D_y H_0$ to be a local diffeomorphism. In this way one can always replace the parameter vector $\omega \in \mathcal{O}$ by the variables $y \in \mathbb{Y}$. We are interested furthermore in also replacing the multi-parameter λ by y in (1.4). In general one can gain one more parameter by time re-parametrization, see section 7c of Broer *et al* (1990)

or Broer and Huitema (1991). In this way the phase space variables $y \in \mathbb{Y}$ take care of all necessary parameters in the case $d = 3$ of the centre–saddle bifurcation (see Hanßmann (1998)).

Using Diophantine approximation of dependent quantities, cf section 2.5 of Broer *et al* (1996a) and references therein, we can generally obtain that y compensates for all parameters (λ, ω) . Given certain non-degeneracy conditions, see lemma 2.13 of Broer *et al* (1996a), this implies that in a given (perturbed) system with Hamiltonian function

$$H = H_0(y, p, q) + \varepsilon H_1(x, y, p, q), \quad (5.2)$$

i.e. without any external parameters, all phenomena of this paper may occur.

Let us explain how to recover the normal form (1.4) from (5.2). Assume that the Taylor series of H_0 near $(p, q) = (0, 0)$ has the form

$$H_0(y, p, q) = h(y) + \frac{a(y)}{2} p^2 + \frac{b(y)}{d!} q^d + \sum_{j=1}^{d-2} \frac{c_j(y)}{j!} q^j + \text{higher order terms}. \quad (5.3)$$

Here the term with q^{d-1} has been cancelled by a suitable translation $q \mapsto q + \tau(y)$; to obtain a symplectic transformation the angular variable has to be simultaneously translated according to $x \mapsto x + D\tau(y)p$. As always, the frequency vector ω is given by $\omega(y) = Dh(y)$. While $a(y)$ and $b(y)$ are bounded from below for $y \in \mathbb{Y}$, the most degenerate bifurcation occurs at $y = 0$ as $c(0) \in \mathbb{R}^{d-2}$ vanishes.

The number of parameters λ_j depends on the degeneracy, d , as the universal unfolding of the singularity q^d requires $d - 2$ parameters (see Bröcker and Lander (1975)). For the corresponding bifurcation diagram to be faithfully represented by means of the y_i , we require the map

$$\begin{aligned} c : \mathbb{R}^n &\longrightarrow \mathbb{R}^{d-2} \\ y &\mapsto c(y) \end{aligned}$$

in (5.3) to be a submersion. This implies $n \geq d - 2$, which is in agreement with the following genericity consideration.

In the present setting of $n + 1$ degrees of freedom, a non-degenerate integrable Hamiltonian system will have n -parameter families of invariant n -tori. Within these, normally elliptic and normally hyperbolic tori are parametrized over open subsets, while normally parabolic tori with dominant terms p^2 and q^{k+2} are expected to form subfamilies of co-dimension $k \in \mathbb{N}$. Indeed, unless forced by additional symmetries, subfamilies of dimension $< n - k$ can avoid such parabolic tori by passing to another integrable system that is a slight perturbation of the former. In this way, bifurcating tori of degeneracy $d > n + 2$ are not encountered.

The non-degeneracy condition (5.1) expresses the idea that the partial derivatives $\partial^{|\ell|} \omega / \partial y^\ell$ span $\mathbb{R}^n$, where $\ell \in \mathbb{N}^n$ with $|\ell| = 1$ ($|\ell| \leq 1$ in the case of iso-energetic non-degeneracy (cf Broer and Huitema (1991))). This allows control of the frequency (the frequency ratio) of the perturbed tori. In the present case of normally parabolic tori the crucial map is

$$\begin{aligned} \nu : \mathbb{R}^n &\longrightarrow \mathbb{R}^{d-2} \times \mathbb{R}^n, \\ y &\mapsto (c(y), \omega(y)) \end{aligned} \quad (5.4)$$

and since we want the first factor, c , to be a submersion, we miss $d - 2$ directions if we restrict ourselves to $|\ell| = 1$. Therefore, we relax the control on the perturbed tori and only aim to show that a perturbed system does have Cantor families of invariant n -tori (according to the hierarchy of co-dimensions of normally parabolic tori addressed in theorem 2.3)—without

trying to further connect the perturbed tori to the unperturbed ones. The proper requirement is that the collection of $\binom{n+L}{n}$ vectors

$$\frac{\partial^{|\ell|} \nu}{\partial y^\ell}, \quad |\ell| \leq L$$

spans $\mathbb{R}^{d-2} \times \mathbb{R}^n$. This implies that the image of ν is ‘sufficiently curved’ and does not lie in any linear hyperplane in $\mathbb{R}^{n+d-2}$ passing through the origin. Since L enters the Diophantine condition (1.1) through $\tau > nL - 1$, it is preferable to keep L as small as possible, i.e. to work with $L = 2$.

In this way we use $c : \mathbb{R}^n \rightarrow \mathbb{R}^{d-2}$ to pull back the bifurcation diagram to the space of actions. The remaining first derivatives together with the higher derivatives of $\nu = (c, \omega)$ then ensure that most frequencies perturbed from the $\omega(y)$ are Diophantine and, hence, yield invariant tori in the perturbed system. Note, however, that for $d = n + 2$ the bifurcating torus is isolated and may disappear in a resonance gap.

5.2. Hierarchy of density strata

In the setting of theorem 2.1, i.e. with ω and λ treated as (external) parameters, the most degenerate normally parabolic tori are parametrized by $\mathcal{O}'_\gamma$; recall that the order of degeneracy is $d - 2$. This set has locally the product structure $\mathbb{R} \times \text{Cantor dust}$; if ω satisfies (1.1), then this holds true for $\beta\omega$, $\beta \geq 1$ as well. Accordingly, the Cantor strata C_k , $k = 1, \dots, d - 2$ of theorem 2.3 locally have the product structure

$$\mathbb{R}^{d-k-1} \times \text{Cantor dust}. \quad (5.5)$$

While these all parametrize normally parabolic tori, the local structure of C_0 depends on whether normally hyperbolic or normally elliptic tori are parametrized. In the former case one may simply put $k = 0$ in (5.5). In the latter case the normal frequency, Ω , enters the Diophantine condition. In the system defined by (1.4), normally elliptic invariant n -tori are given by $y = 0 = p$ and $(\hat{q}, \hat{\lambda})$ satisfying

$$\frac{b(\omega)}{(d-1)!} \hat{q}^{d-1} + \sum_{j=0}^{d-3} \frac{\hat{\lambda}_{j+1}}{j!} \hat{q}^j = 0 \quad \text{and} \quad \text{sgn}(a(\omega)) \left(\frac{b(\omega)}{(d-2)!} \hat{q}^{d-2} + \sum_{j=0}^{d-4} \frac{\hat{\lambda}_{j+2}}{j!} \hat{q}^j \right) > 0,$$

whence

$$\Omega = \sqrt{a(\omega) \left(\frac{b(\omega)}{(d-2)!} \hat{q}^{d-2} + \sum_{j=0}^{d-4} \frac{\hat{\lambda}_{j+2}}{j!} \hat{q}^j \right)}$$

is the normal frequency. To obtain persistence, the Diophantine condition (1.1) has to be replaced by

$$|(\omega \mid k) + \Omega \ell| \geq \frac{\gamma}{|k|^\tau}, \quad \forall_{k \in \mathbb{Z}^n \setminus \{0\}} \quad \forall_{\ell \in \{0, \pm 1, \pm 2\}},$$

see Pöschel (1989), Broer *et al* (1990) or Broer *et al* (1996a). Consequently, one has to put $k = 1$ in (5.5) to obtain the local product structure of the Cantor set parametrizing the persistent normally elliptic tori. We remark that the ‘additional’ Diophantine conditions, with $\ell \neq 0$, exclude smaller and smaller subsets as $\Omega \rightarrow 0$. This implies that normally parabolic tori consist of Lebesgue density points of normally elliptic tori.

Remark 5.1. For this analysis of the Cantor sets C_k we used the new coordinates provided by theorem 2.1. The transformation Φ respects the fact that the coordinates x, y, p, q are distinguished with respect to the parameters λ and ω , i.e.

$$\Phi(x, y, p, q; \lambda, \omega) = (\phi(x, y, p, q; \lambda, \omega); \mu(\lambda, \omega)).$$

A close inspection of the proof in section 6.1.3 reveals that furthermore the parameter λ is distinguished with respect to ω , i.e.

$$\mu(\lambda, \omega) = (\mu_1(\lambda, \omega), \mu_2(\omega)).$$

Indeed, at every iteration step we have

$$\omega_+ = \omega + P_{01000}(\omega),$$

where P_{01000} is the x -average of the coefficient of y of the perturbation P expanded in (y, p, q, λ) . Therefore, the Cantor set structure of the C_k remains valid in the original variables as well.

When using the mapping $\nu : \mathbb{Y} \longrightarrow \Lambda \times \mathcal{O}$ defined in (5.4) to let the phase space variables y account for the parameters (λ, ω) , the strata C_k of theorem 2.3 get replaced by the Cantor sets $\nu^{-1}(C_k)$ of the respective (Hausdorff)-dimension $n - k$. Therefore, the local structure of the Cantor set parametrizing normally hyperbolic tori becomes $\mathbb{R} \times$ Cantor dust, while the Cantor set parametrizing normally elliptic tori and all strata parametrizing normally parabolic tori become Cantor dust. Note that ‘higher strata’ $\nu^{-1}(C_{k+1})$ consist of Lebesgue density points of ‘lower strata’ $\nu^{-1}(C_k)$. Indeed, this is inherited from the Cantor stratification of $\Lambda \times \mathcal{O}$ into $\bigcup C_k$.

6. Proof of theorem 2.1

In this section we give a detailed proof of theorem 2.1, following the quite universal set-up of Moser (1967), Pöschel (1989) and Broer *et al* (1990). Our aim is to obtain a coordinate transformation Φ that pushes the perturbation P of the normal form, N , into higher order terms and thus allows us to recover the bifurcation scenario imposed by N in the perturbed system. We only expect those invariant tori to survive that satisfy a strong form of quasi-periodicity and concentrate on Diophantine frequency vectors. Therefore, we construct Φ as a limit of a sequence of transformations $(\Phi_\nu)_{\nu \in \mathbb{N}}$ defined on shrinking open neighbourhoods of our set $\mathcal{O}'_\gamma$ of Diophantine frequency vectors.

In fact we first fix the Diophantine constant $\gamma = 1$ when proving theorem 2.1. This allows a more transparent argumentation where the sizes β_ν of the shrinking neighbourhoods of $\mathcal{O}'_1$ are effectively decoupled from the Diophantine constant $\gamma > 0$. A simple scaling argument given in section 6.3 allows us to extend the result thus obtained to the $\mathcal{O}'_\gamma$ of theorem 2.1.

To ensure that the limit is Whitney- C^∞ -smooth in ω , we work on domains $\mathcal{D}(r_\nu, s_\nu, \beta_\nu)$ that shrink geometrically in the x - and ω -directions. Then an exponentially fast decreasing sequence $(\varepsilon_\nu)_{\nu \in \mathbb{N}}$ that controls at the ν th step the (transformed) perturbation P_ν allows us to use the inverse approximation lemma of Zehnder (1975) for the desired Whitney- C^∞ -smoothness. The necessary control of P_ν is in turn obtained by letting $\mathcal{D}(r_\nu, s_\nu, \beta_\nu)$ shrink exponentially, described by $s_\nu = \varepsilon_\nu^{1/(2d+\sigma)}$ with $\sigma \in]0, 1[$, in the $(y, p, q; \lambda)$ -directions. The limit

$$\bigcap_{\nu} \mathcal{D}(r_\nu, s_\nu, \beta_\nu)$$

consists of the ω -direction exactly of the set $\mathcal{O}'_1$ of Diophantine frequency vectors, while it shrinks to $\{0\}$ in the $(y, p, q; \lambda)$ -directions. Analyticity in the latter variables is then obtained by interpreting the limit functions as the (x, ω) -dependent coefficients of polynomials like N_∞ .

An additional complication is that a mere polynomial truncation of the Φ_ν would cease to preserve the symplectic structure. For this reason we introduce generating functions S_ν of Φ_ν , the polynomial truncations $\tilde{S}_\nu$ of which generate symplecto-morphisms as well. The limit $\tilde{S}_\infty$ of these then generates the desired Φ_∞ .

We define the ν th transformation,

$$\Phi_\nu = \Psi_0 \circ \Psi_1 \circ \cdots \circ \Psi_{\nu-1},$$

where

$$\Psi_{\nu-1} : \mathcal{D}(r_\nu, s_\nu, \beta_\nu) \longrightarrow \mathcal{D}(r_{\nu-1}, s_{\nu-1}, \beta_{\nu-1}).$$

At each iteration step we want $\Psi_{\nu-1}$ to solve two problems. The x -dependence has to be confined to the new (and smaller) perturbation, P_ν , and the x -independent terms have to be transformed into normal form, N_ν . We can explicitly decouple the solution of these two problems and construct

$$\Psi_{\nu-1} = \varphi_{\nu-1} \circ \phi_{\nu-1}.$$

This is in sharp contrast with the (otherwise similar) approach in Braaksma and Broer (1987), Braaksma *et al* (1990) and Hanßmann (1998), where these two problems were addressed simultaneously. Thus, $\varphi_{\nu-1}$ is the solution of the linearized (or ‘1-bite’) small denominator problem and $\phi_{\nu-1}$ uses explicit transformations from singularity theory to put the (now x -independent) lower order terms again into normal form (1.4).

In this way the method of proof follows the standard KAM recipe, inspired by the iterative schemes of, e.g., Moser (1967) and Pöschel (1989). At the ν th step we have a perturbation form $H_\nu = N_\nu + P_\nu$ with N_ν in normal form (1.4) and P_ν sufficiently small. Although not of dynamical importance, one should in fact introduce a constant term $e_\nu = e_\nu(\lambda, \omega)$ to compensate for constant terms introduced by P_ν . Since it is *a priori* clear that these do not add up to ∞ , we do not burden our presentation with these constant terms and suppress them at every stage.

In the limit we obtain $H_\infty = N_\infty + P_\infty$, where P_∞ no longer has any influence on the tori at $\lambda = 0$ and their normal behaviour, thus yielding the desired persistence result.

One of the basic tools of the KAM method is Cauchy’s inequality. Here the analyticity of our Hamiltonian functions comes into play, allowing us to control derivatives by the supremum norm on complex domains. Therefore, we extend the Hamiltonian H into a complex domain,

$$\mathcal{D}(r_0, s_0, \beta_0) = \mathcal{D}(r_0, s_0) \times U_{\beta_0}(\mathcal{O}),$$

where

$$\mathcal{D}(r_0, s_0) = \{(x, y, p, q; \lambda) \mid |\operatorname{Im} x| \leq r_0, |y| \leq s_0^{2d}, |p| \leq s_0^d, |q| \leq s_0^2, |\lambda_j| \leq s_0^{2d-2j}\}$$

and the second factor is a complex β_0 -neighbourhood,

$$U_{\beta_0}(\mathcal{O}) = \{w \in \mathbb{C}^n \mid \exists \omega \in \mathcal{O} |w - \omega| < \beta_0\},$$

of the set $\mathcal{O} \subseteq \mathbb{R}^n$ of all frequency vectors, and assume that $|P| \leq \varepsilon_0$ in $\mathcal{D}(r_0, s_0, \beta_0)$. Relating ε_ν to s_ν through $\varepsilon_\nu = s_\nu^{2d+\sigma}$, we require the perturbation part, P_ν , of H_ν to satisfy

$$|P_\nu| \leq \varepsilon_\nu$$

in the shrinking domain

$$\mathcal{D}(r_\nu, s_\nu, \beta_\nu) = \mathcal{D}(r_\nu, s_\nu) \times U_{\beta_\nu}(\mathcal{O}'_1),$$

where

$$\mathcal{D}(r_\nu, s_\nu) = \{(x, y, p, q; \lambda) \mid |\operatorname{Im} x| \leq r_\nu, |y| \leq s_\nu^{2d}, |p| \leq s_\nu^d, |q| \leq s_\nu^2, |\lambda_j| \leq s_\nu^{2d-2j}\}$$

and the β_ν -neighbourhood is only taken of the Diophantine frequency vectors in $\mathcal{O}'_1$. Here s_ν and ε_ν converge exponentially to 0, while r_ν converges geometrically to $\frac{1}{2}r_0$ and β_ν is related to r_ν , converging (geometrically) to 0. For the precise definition of all these sequences see (6.4). We motivate the choice of the weights $2d, d, 2$ and $2d - 2j$ in definition 6.3, see section 6.1.2.

6.1. The iteration step

The aim of a single step of the KAM iteration is to find a coordinate transformation that turns the given Hamiltonian H_ν into a ‘new’ Hamiltonian $H_{\nu+1}$ that differs ‘less’ from the normal form $N_{\nu+1}$. To this end we re-write H_ν as

$$H_\nu = N_\nu + R_\nu + (P_\nu - R_\nu),$$

where R_ν is a conveniently chosen higher order truncation of P_ν , see (6.9). We show below how the Newton-like accelerated convergence implies that $|P_\nu - R_\nu|$ is less than $|P_\nu|_{\mathcal{D}}^\kappa$, $\kappa > 1$, on the smaller domain $\mathcal{D}(r_{\nu+1}, s_{\nu+1}, \beta_{\nu+1})$.

Let F_ν be a function defined in a domain $\mathcal{D} \subseteq \mathcal{D}(r_\nu, s_\nu, \beta_\nu)$ and let X_{F_ν} be the vector field with Hamiltonian function F_ν . Denote by $\varphi_t^{F_\nu}$ the flow of X_{F_ν} and $\varphi_{F_\nu} := \varphi_{t=1}^{F_\nu}$. We then have

$$\begin{aligned} H_\nu \circ \varphi_{F_\nu} &= (N_\nu + R_\nu) \circ \varphi_{F_\nu} + (P_\nu - R_\nu) \circ \varphi_{F_\nu} \\ &= N_\nu + R_\nu + \{N_\nu, F_\nu\} + \{R_\nu, F_\nu\} \\ &\quad + \int_0^1 (1-t) \{ \{N_\nu + R_\nu, F_\nu\}, F_\nu \} \circ \varphi_t^{F_\nu} dt + (P_\nu - R_\nu) \circ \varphi_{F_\nu} \\ &= N_\nu + R_\nu + \{N_\nu, F_\nu\} + \bar{P}_\nu. \end{aligned} \quad (6.1)$$

The philosophy of the KAM method is to find a special F_ν defined in a shrunken domain which makes the new perturbation, $\bar{P}_\nu$, in (6.1) much smaller and $N_\nu + R_\nu + \{N_\nu, F_\nu\}$ a new normal form, $N_{\nu+1}$. In the present context by this notion we not only mean a Hamiltonian function that is independent of the angles x , i.e. integrable, but that furthermore defines a versal unfolding of the bifurcating tori at $\lambda = 0$. In the case of normally elliptic or hyperbolic tori, we do not need to put the higher order terms of q into the normal form; F_ν is thus obtained by solving a linear partial differential equation, the so-called homological equation

$$N_\nu + R_\nu + \{N_\nu, F_\nu\} = N_{\nu+1}, \quad (6.2)$$

where

$$\{N, F\} = \frac{\partial N}{\partial x} \frac{\partial F}{\partial y} - \frac{\partial N}{\partial y} \frac{\partial F}{\partial x} + \frac{\partial N}{\partial q} \frac{\partial F}{\partial p} - \frac{\partial N}{\partial p} \frac{\partial F}{\partial q}.$$

In the present bifurcating case, since N_ν contains higher order terms in q , equation (6.2) cannot be solved completely. Note that the purpose of solving (6.2) is to find a function F_ν so that (6.1) becomes the sum of a new normal form and a smaller perturbation. To achieve this, we split the iteration step into two parts.

- (i) Instead of solving (6.2), we solve the ‘intermediate homological equation’

$$N_\nu + R_\nu + \{N_\nu, F_\nu\} = \bar{N}_\nu \quad (6.3)$$

up to some order and treat the higher order terms (which are smaller) as a part of the new perturbation. The ‘intermediate’ $\bar{N}_\nu$, already independent of x , but not yet normalized in p and q , is defined later in (6.13). The solution of (6.3) leads to small denominators, whence the Diophantine conditions (1.1) are needed. For the ν th iteration step we only use finitely many of these conditions, up to some ‘ultraviolet’ cut-off for the order K_ν of the Fourier truncation (6.9) defined in (6.4) below.

- (ii) Then we look for a symplectic change of variables which transforms $\bar{N}_\nu$ into normal form (1.4). This passage from $\bar{N}_\nu$ to $N_{\nu+1}$ does not involve small denominators but requires methods from singularity theory instead.

6.1.1. The iteration lemma. To formulate the iteration lemma we need several convergent sequences of numbers, and the interplay of geometrically fast and exponentially fast convergence later on yields the desired (Whitney)-smoothness. For any given positive numbers r_0, s_0 we recursively define the following sequences:

$$\begin{aligned}\rho_v &= \frac{\rho_{v-1}}{4} = \frac{1}{4^v} \cdot \frac{3r_0}{32}, \\ r_v &= r_{v-1} - 4\rho_{v-1} = \frac{r_0}{2} \left(1 + \frac{1}{4^v}\right), \\ \beta_v &= \rho_v^{2\tau+2}, \\ K_v &= [\beta_v^{-1/(\tau+1)}] = [\rho_v^{-2}], \\ s_v &= s_{v-1}^{\kappa/(2d+\sigma)} s_{v-1} = s_0^{(1+\kappa/(2d+\sigma))^v}, \\ \varepsilon_v &= s_v^{2d+\sigma}\end{aligned}\tag{6.4}$$

with $0 < \kappa < \sigma < 1$. The constants in the estimates below will be absorbed in r_0 and s_0 , leading to inequalities of the form

$$r_0 \leq c, \quad s_0 \leq c, \quad s_0^\varsigma \leq cr_0,$$

with constants $c > 0$ and exponents $\varsigma > 0$. The only exception is lemma 6.5, where an inequality

$$r_0 < \frac{1}{c - \varsigma \ln(s_0)}\tag{6.5}$$

occurs. Since $s_0^\varsigma \ln(s_0) \xrightarrow{s_0 \rightarrow 0} 0$ for all $\varsigma > 0$, it is possible to find small r_0, s_0 satisfying all these inequalities.

With these sequences at hand we now can formulate the iteration lemma. We consider a Hamiltonian function

$$H_v = N_v + P_v\tag{6.6}$$

with

$$N_v = (\omega \mid y) + \frac{a_v}{2} p^2 + \frac{b_v}{d!} q^d + \sum_{j=1}^{d-2} \frac{\lambda_j}{j!} q^j\tag{6.7}$$

and defined in

$$\mathcal{D}_v := \mathcal{D}(r_v, s_v, \beta_v) = D(r_v, s_v) \times U_{\beta_v}(\mathcal{O}'_1).$$

We also use the abbreviation

$$U_v := U_{\beta_v}(\mathcal{O}'_1)$$

for the β_v -neighbourhood in the second factor.

Lemma 6.1. Suppose that $H_v = N_v + P_v$ satisfies (6.7) in $\mathcal{D}_v$ and that P_v can be estimated by

$$|P_v|_{\mathcal{D}_v} \leq \varepsilon_v.\tag{6.8}$$

Then, for sufficiently small s_0 , there is a symplectic change of variables

$$\Psi_v : \mathcal{D}_{v+1} \longrightarrow \mathcal{D}_v$$

such that $H_{v+1} = H_v \circ \Psi_v$, defined on $\mathcal{D}_{v+1}$, has the form

$$H_{v+1} = N_{v+1} + P_{v+1},$$

satisfying

$$\begin{aligned} |P_{v+1}|_{\mathcal{D}_{v+1}} &\leq \varepsilon_{v+1}, \\ |a_{v+1} - a_v|_{U_{v+1}} &\leq s_v, \\ |b_{v+1} - b_v|_{U_{v+1}} &\leq s_v. \end{aligned}$$

Moreover,

$$\left| \frac{\partial^{|l|+i+j+h} P_{v+1}}{\partial y^l \partial p^i \partial q^j \partial \lambda^h} \right|_{\mathcal{D}_{v+1}} \leq s_{v+1}^{2d+\sigma-m},$$

where $m := 2d|l| + di + 2j + (2d - 2)h_1 + \dots + 4h_{d-2} \leq 2d$.

Remark 6.2. Compared with the perturbation, the coefficient functions a_v and b_v are of order 1, i.e. they satisfy bounds as formulated in theorem 2.1. The estimates by s_v on the differences $|a_{v+1} - a_v|$, $|b_{v+1} - b_v|$ imply that the same is true for a_{v+1} and b_{v+1} as well and also for the (existing) limit functions a_∞ and b_∞ .

6.1.2. The intermediate homological equation To prove lemma 6.1 we describe a single iteration step in detail. Therefore, we drop the index v and use the so-called ‘+’-notation, replacing occurrences of the index $v+1$ by an index $+$. As said earlier, we look for a symplectic coordinate transformation such that the transformed Hamiltonian function satisfies (6.6)–(6.8) with s_+ , ε_+ and so on. This also emphasizes that the constants in our estimates have to be independent of v . The generic letter ‘ c ’ is used where we do not need to remember the value of such a constant, and we also use the shorthand $A \leq B$ for $A \leq c \cdot B$. Adapted to the normal form (1.4), we introduce the concept of quasi-homogeneous polynomials with weight (cf Arnol’d *et al* (1993)).

Definition 6.3. A polynomial $F(y, p, q; \lambda_1, \dots, \lambda_k)$ is said to be quasi-homogeneous of order m with weight $(\alpha_y, \alpha_p, \alpha_q; \alpha_1, \dots, \alpha_k)$ if

$$F(e^{\alpha_y s} y, e^{\alpha_p s} p, e^{\alpha_q s} q; e^{\alpha_1 s} \lambda_1, \dots, e^{\alpha_k s} \lambda_k) \equiv e^{ms} F(y, p, q; \lambda_1, \dots, \lambda_k),$$

where m is a positive integer.

Remark 6.4. In this way

$$N = (\omega | y) + \frac{a}{2} p^2 + \frac{b}{d!} q^d + \sum_{j=1}^{d-2} \frac{\lambda_j}{j!} q^j$$

is a $2d$ th order quasi-homogeneous polynomial with weight $(2d, d, 2; 2d - 2, \dots, 4)$. This weight in turn induces the weighted order

$$\|(l, i, j, h)\| := 2d|l| + di + 2j + (2d - 2)h_1 + \dots + 4h_{d-2}$$

on indices

$$l = (l_1, \dots, l_n) \in \mathbb{N}_0^n, \quad i, j \in \mathbb{N}_0, \quad h = (h_1, \dots, h_{d-2}) \in \mathbb{N}_0^{d-2}.$$

On the ring of all (= formal) power series in y, p, q and λ this defines in the terminology of Bourbaki (1985) a *gradation*

$$\mathcal{A}_m := \left\{ F \in \mathbb{C}[y, p, q, \lambda] \mid \begin{array}{l} F \text{ quasi-homogeneous of order } m \\ \text{with weight } (2d, d, 2; 2d - 2, \dots, 4) \end{array} \right\}$$

together with the *filtration* $\mathcal{F}_n := \prod_{m \geq n} \mathcal{A}_m$. With this terminology we may write

$$F = G \pmod{\mathcal{F}_{2d}}$$

if all monomials up to weighted order $2d$ in the power series F and G have equal coefficients.

We expand the perturbation P into a Fourier–Taylor series

$$P(x, y, p, q; \lambda, \omega) = \sum_{m=0}^{\infty} \sum_{\|(l,i,j,h)\|=m} \sum_{k \in \mathbb{Z}^n} P_{klijh} e^{i(k|x)} y^l p^i q^j \lambda^h$$

and define the truncation

$$R = \sum_{|k| \leq K} P_k e^{i(k|x)} \quad (6.9)$$

of P with

$$P_k(y, p, q; \lambda, \omega) = \sum_{m \leq 2d} P_{km} = \sum_{m \leq 2d} \left(\sum_{\|(l,i,j,h)\|=m} P_{klijh} y^l p^i q^j \lambda^h \right). \quad (6.10)$$

Here $|k| = K$, with $K = [\beta^{-1/(\tau+1)}]$, is the maximal order $|k| = |k_1| + \dots + |k_n|$ of the resonances we have to cope with at this stage. We need bounds on both the truncation R of P we use to define the coordinate transformation (by solving (6.3)) and on the remaining term $P - R$ which will be included in the new (and smaller!) perturbation.

Lemma 6.5. *Under the conditions of lemma 6.1 the inequality*

$$|R|_{\mathcal{D}(r-\rho, (1/2)s, \beta)} \leq \varepsilon \quad (6.11)$$

holds. Moreover, on a smaller domain we have

$$|P - R|_{\mathcal{D}(r-\rho, \alpha s, \beta)} \leq \alpha^{1-\sigma} s^\kappa \varepsilon \quad (6.12)$$

where $\alpha = 9s^{\kappa/(2d+\sigma)}$.

Proof. We only prove (6.12), since (6.11) can be obtained from the following proof by taking $\alpha = \frac{1}{2}$. Note that

$$P - R = \sum_{\substack{m \leq 2d \\ |k| > K}} P_{km} e^{i(k|x)} + \sum_{\substack{m > 2d \\ k \in \mathbb{Z}^n}} P_{km} e^{i(k|x)}.$$

To estimate the first term we use the Paley–Wiener estimate and an upper bound of the number of vectors $k \in \mathbb{Z}^n$ with $|k| = \mu$ to obtain

$$\begin{aligned} \left| \sum_{\substack{m \leq 2d \\ |k| > K}} P_{km} e^{i(k|x)} \right| &\leq \sum_{|k| > K} |P|_{\mathcal{D}} e^{-|k|r} e^{|k|(r-\rho)} \leq \varepsilon \sum_{\mu=K+1}^{\infty} \mu^n e^{-\mu\rho} \\ &\leq \varepsilon \int_K^{\infty} x^n e^{-\rho x} dx \leq K^n e^{-K\rho} \varepsilon. \end{aligned}$$

Using $K = [\beta^{-1/(\tau+1)}]$ and $\beta = \rho^{2\tau+2}$ we continue

$$K^n e^{-K\rho} \varepsilon \leq \rho^{-2n} e^{-1/(2\rho)} \varepsilon \leq s\varepsilon,$$

where the last inequality is given by lemma 5.10 of Braaksma and Broer (1987). The condition of that lemma leads to the inequality (6.5). For the second term we use the fact that we may shrink the domain in the y, p, q and λ direction and get

$$\begin{aligned} \left| \sum_{\substack{m > 2d \\ k \in \mathbb{Z}^n}} P_{km} e^{i(k|x)} \right| &\leq \left| \int \frac{\partial^{|l|+|i|+|j|+|h|}}{\partial y^l \partial p^i \partial q^j \partial \lambda^h} \sum_{\substack{m > 2d \\ k \in \mathbb{Z}^n}} P_{km} e^{i(k|x)} dy^l dp^i dq^j d\lambda^h \right| \\ &\leq \frac{(\alpha s)^{2d+1}}{s^{2d+1}} \left| \sum_{m=0}^{\infty} \sum_{k \in \mathbb{Z}^n} P_{km} e^{i(k|x)} \right| \leq \alpha^{2d+1} \varepsilon \end{aligned}$$

in $\mathcal{D}(r - \rho, \alpha s, \beta)$, where $\int$ stands for

$$\underbrace{\int_0^{y_1} \cdots \int_0^{y_1}}_{l_1} \cdots \underbrace{\int_0^{y_n} \cdots \int_0^{y_n}}_{l_n} \underbrace{\int_0^p \cdots \int_0^p}_i \underbrace{\int_0^q \cdots \int_0^q}_j \underbrace{\int_0^{\lambda_1} \cdots \int_0^{\lambda_1}}_{h_1} \cdots \underbrace{\int_0^{\lambda_{d-2}} \cdots \int_0^{\lambda_{d-2}}}_{h_{d-2}}$$

with $\|(l, i, j, h)\| = 2d + 1$.

QED

Our next goal is to solve the intermediate homological equation (6.3). To this end we add the average of (6.9) to N , i.e. we let

$$\bar{N} = N + P_0(y, p, q; \lambda, \omega), \quad (6.13)$$

where

$$P_0(y, p, q; \lambda, \omega) = \sum_{j=1}^d P_j(\lambda) q^j + \sum_{j=0}^{[d/2]} Q_j(\lambda) p q^j + P_{00200} p^2 + (P_{01000}|y)$$

is given by (6.10) with

$$P_j(\lambda) = \sum_{2(d-1)h_1 + \cdots + 4h_{d-2} \leq 2d-2j} P_{000jh} \lambda^h,$$

$$Q_j(\lambda) = \sum_{2(d-1)h_1 + \cdots + 4h_{d-2} \leq d-2j} P_{001jh} \lambda^h.$$

Here and below we completely suppress the ω -dependence, in particular the coefficients $P_{0lijh} = P_{0lijh}(\omega)$ are functions on $U = U_\beta(\mathcal{O}'_1)$. Recall that we ignore the constant terms $P_{0000h} \lambda^h$. Since we cannot solve (6.3) completely, we let

$$F = \sum_{0 < |k| \leq K} F_k e^{i(k|x)},$$

$$F_k = \sum_{m \leq 2d} F_{km} = \sum_{m \leq 2d} \left(\sum_{\|(l,i,j,h)\|=m} F_{klijh} y^l p^i q^j \lambda^h \right),$$

be the solution of

$$N + R + \{N, F\} = \bar{N} \pmod{\mathcal{F}_{2d}},$$

i.e. up to weighted order $2d$. The coefficients of the function F can be defined inductively by

$$\begin{aligned} i(k | \omega) F_{km} &= P_{km} + \left(\frac{b}{(d-1)!} q^{d-1} + \sum_{j=1}^{d-2} \frac{\lambda_j}{(j-1)!} q^{j-1} \right) \frac{\partial F_{k,m+2-d}}{\partial p} - ap \frac{\partial F_{k,m+2-d}}{\partial q} \\ &= P_{km} + \{N_0, F_{k,m+2-d}\}, \end{aligned}$$

where $N_0 = \frac{1}{2}ap^2 + (b/d!)q^d + \sum_{j=1}^{d-2} (\lambda_j/j!)q^j$. More precisely,

$$F_{km} = \Delta P_{km} + \sum_{i=1}^6 \Delta^{i+1} \underbrace{\{N_0, \dots, \{N_0, P_{k,m-i(d-2)}\} \dots\}}_i. \quad (6.14)$$

Here we define $P_{km} = 0$ if $m < 0$ and denote $\Delta = 1/(i(k | \omega))$ for simplicity. We stress that since

$$m - 6(d-2) \leq 2d - 6(d-2) = 12 - 4d \leq 0,$$

the right-hand side of (6.14) contains at most seven terms.

Remark 6.6. Since we only solved equation (6.3) up to the weighted order $2d$, the higher order terms

$$\{N_0, \sum_{\substack{0 < |k| \leq K \\ d+2 < m \leq 2d}} F_{km} e^{i(k|x)}\}$$

have to be included in the new perturbation.

To estimate the nested Poisson brackets in (6.14) we work on the nested domains

$$\mathcal{D}^i = \mathcal{D}\left(r - \frac{3+i}{4}\rho, \frac{1}{1+i}s, \frac{\beta}{2}\right) \subset \mathcal{D}^1 = \mathcal{D}\left(r - \rho, \frac{1}{2}s, \frac{\beta}{2}\right), \quad i = 1, \dots, 8$$

and later use the four domains

$$\mathcal{D}^{i\alpha} = \mathcal{D}\left(r - \frac{11+i}{4}\rho, 2^{1-i}\alpha s, \frac{7-i}{12}\beta\right) \subset \mathcal{D}^\alpha = \mathcal{D}\left(r - 3\rho, \alpha s, \frac{\beta}{2}\right), \quad i = 1, \dots, 4$$

to define the normalizing coordinate transformation. For Poisson brackets with N_0 we have the inequality

$$| \{N_0, G\} |_{\mathcal{D}^i} = \left| \frac{\partial N_0}{\partial q} \frac{\partial G}{\partial p} - \frac{\partial N_0}{\partial p} \frac{\partial G}{\partial q} \right|_{\mathcal{D}^i} \leq s^{d-2} |G|_{\mathcal{D}^{i-1}}.$$

Lemma 6.7. Under the conditions of lemma 6.1 we have

$$|F|_{\mathcal{D}^7} \leq \varepsilon.$$

Proof. Expanding

$$\begin{aligned} F &= \sum_{0 < |k| \leq K} F_k e^{i(k|x)} = \sum_{\substack{0 < |k| \leq K \\ m \leq 2d}} F_{km} e^{i(k|x)} \\ &= \sum_{i=0}^6 \Delta^{i+1} \underbrace{\{N_0, \dots, \{N_0, \sum_{\substack{0 < |k| \leq K \\ m \leq 2d}} P_{k, m-i(d-2)} e^{i(k|x)}\} \dots\}}_i, \end{aligned}$$

we obtain

$$\begin{aligned} |F|_{\mathcal{D}^7} &\leq \left| \sum_{\substack{0 < |k| \leq K \\ m \leq 2d}} \sum_{i=0}^6 \Delta^{i+1} \underbrace{\{N_0, \dots, \{N_0, P_{k, m-i(d-2)}\} \dots\}}_i e^{i(k|x)} \right|_{\mathcal{D}^7} \\ &\leq \sum_{\substack{0 < |k| \leq K \\ m \leq 2d}} \sum_{i=0}^6 |\Delta|^{i+1} s^{(d-2)i} |P_{k, m-i(d-2)}|_{\mathcal{D}^{7-i}} e^{|k|(r-\rho)} \\ &\leq \sum_{|k| \leq K} \sum_{i=0}^6 |(k|\omega)|^{-i-1} s^{(d-2)i} |P|_{\mathcal{D}} e^{-|k|\rho}, \end{aligned}$$

where we again used the Paley–Wiener estimate. Given ω , there exists $w \in \mathcal{O}'_1$ with $|\omega - w| \leq \frac{1}{2}\beta$, and from $K = [\beta^{-1/(\tau+1)}]$ we obtain

$$|(k|\omega)| \geq |(k|w)| - |\omega - w| \cdot |k| \geq |k|^{-\tau} - \frac{1}{2}\beta K \geq |k|^{-\tau} - \frac{1}{2}K^{-\tau} \geq \frac{1}{2}|k|^{-\tau},$$

whence the inequality

$$\sum_{k \in \mathbb{Z}} |k|^{7\tau} e^{-|k|\rho} \leq \rho^{-8\tau}$$

allows us to conclude the proof. QED

Remark 6.8. Since $(\rho_\nu)_\nu$ decreases geometrically and $(s_\nu)_\nu$ decreases exponentially fast we also include factors $1/\rho_\nu$ in the ‘generic constant c ’, taking care that the total number of such factors remains finite (and independent of ν).

By the Cauchy estimate we have

$$\left| \frac{\partial^{|l|+i+j+h} F}{\partial y^l \partial p^i \partial q^j \partial \lambda^h} \right|_{\mathcal{D}^8} \leq s^{-m} \varepsilon \quad (6.15)$$

if $\|(l, i, j, h)\| \leq m$. Denote by

$$\|X_F\|_{\mathcal{D}} := \max \left\{ \left| \frac{\partial F}{\partial y} \right|_{\mathcal{D}}, s^{-2d} \left| \frac{\partial F}{\partial x} \right|_{\mathcal{D}}, s^{-2d+2} \left| \frac{\partial F}{\partial q} \right|_{\mathcal{D}}, s^{-d} \left| \frac{\partial F}{\partial p} \right|_{\mathcal{D}} \right\},$$

$$\uparrow D_\mu X_F \uparrow_{\mathcal{D}} = \max_{|l|+i+j \leq \mu} \left\{ \left| \frac{\partial^{|l|+i+j} G}{\partial y^l \partial p^i \partial q^j} \right|_{\mathcal{D}} \right\} \quad \text{for } \mu \geq 1,$$

where G stands for one of $\partial F/\partial y$, $\partial F/\partial x$, $\partial F/\partial q$, $\partial F/\partial p$. From the Cauchy estimates we obtain a bound cs^σ of the Hamiltonian vector field X_F . As F is a polynomial in y , p and q with weighted order $2d$, such a bound even holds for the partial derivatives $(\partial^{|l|+i+j}/\partial y^l \partial p^i \partial q^j)X_F$.

Lemma 6.9. *Under the conditions of lemma 6.1 we have*

$$\|X_F\|_{\mathcal{D}^8} \leq s^\sigma, \quad \uparrow D_\mu X_F \uparrow_{\mathcal{D}^8} \leq s^\sigma \quad \forall \mu \geq 1.$$

Proof. This is an immediate consequence of (6.15) and $\varepsilon = s^{2d+\sigma}$. Indeed, the expressions $(\partial^{|l|+i+j}/\partial y^l \partial p^i \partial q^j)G$ are either partial derivatives of F of weighted order $\leq 2d$, or vanish identically. QED

Hence, the flow φ_t^F of X_F satisfies $\|\varphi_t^F - \text{id}\|_{\mathcal{D}^8} \leq c|t|s^\sigma$ as well, i.e. the first, second, third and fourth components of $\varphi_t^F - \text{id}$ are bounded by $c|t|s^\sigma$, $c|t|\varepsilon$, $c|t|s^{-2}\varepsilon$ and $c|t|s^{d+\sigma}$, respectively. Therefore, the inequality $s^{2d(\sigma-\kappa)/(2d+\sigma)} \leq 1/2c$ implies that, for $-1 \leq t \leq 1$, the flow φ_t^F not only maps $\mathcal{D}^8$ into $\mathcal{D}^7$ but also maps $\mathcal{D}^{2\alpha}$ into $\mathcal{D}^\alpha$. Here we slightly abuse notation in that the same symbol, φ_t^F , is used for the mapping acting as the identity in the fifth and sixth components. Furthermore, we have the following estimate for $\varphi_F = \varphi_{t=1}^F$, the time one map of the Hamiltonian flow φ_t^F . The norm for φ_F is defined by

$$\|\varphi_F\|_{C^{ij}(\mathcal{D})} = \max_{0 \leq t \leq 1} \left\| \frac{\partial^{|l|+i+j} \varphi_t^F}{\partial y^l \partial p^i \partial q^j} \right\|_{\mathcal{D}}.$$

We also define

$$(A \bullet B)(t) := A(t) \circ B(t)$$

for two mapping-valued mappings A and B .

Lemma 6.10. *For any given l, i, j there is a constant s_0 , depending only on n, τ and $|l|+i+j$, such that if $s \leq s_0$*

$$\|\varphi_F - \text{id}\|_{C^{ij}(\mathcal{D}^{2\alpha})} \leq s^\sigma.$$

Proof. Note that φ_t^F satisfies the integral equation

$$\varphi_t^F = \text{id} + \int_0^t X_F \circ \varphi_{\tilde{t}}^F d\tilde{t}$$

from which we derive for the (total) derivatives of order $\mu \geq 2$

$$D^\mu \varphi_F = 0 + \int_0^1 \sum c_{\ell t}^\mu ((D^\ell X_F) \circ \varphi_t^F) \bullet (D^{\ell_1} \varphi_t^F, \dots, D^{\ell_\mu} \varphi_t^F) dt, \quad (6.16)$$

where the sum is taken over $\ell = 1, \dots, \mu$ and $\iota_1 \geq \dots \geq \iota_\ell \geq 1$ with $\iota_1 + \dots + \iota_\ell = \mu$. Partial derivatives on the left-hand side that do not differentiate with respect to x involve on the right-hand side only partial derivatives with at most one differentiation with respect to x . For the first derivative we have

$$\uparrow D\varphi_F \uparrow_{\mathcal{D}^{2\alpha}} \leq 1 + \uparrow DX_F \uparrow_{\mathcal{D}^\alpha} \cdot \uparrow D\varphi_F \uparrow_{\mathcal{D}^{2\alpha}}.$$

When $|l| + i + j = 1$ lemma 6.9 yields

$$\left\| \frac{\partial^{|l|+i+j} \varphi_F}{\partial y^l \partial p^i \partial q^j} \right\|_{\mathcal{D}^{2\alpha}} \leq \uparrow D\varphi_F \uparrow_{\mathcal{D}^{2\alpha}} \leq \frac{1}{1 - cs^\sigma} \leq 2,$$

if s_0 is sufficiently small. This immediately implies the desired result for $|l| + i + j = 1$. Inductively, assuming the proper bound on $(\partial^{|l|+i+j} / \partial y^l \partial p^i \partial q^j) \varphi_F$ holds for $|l| + i + j \leq \mu - 1$, from (6.16) we have

$$\left\| \frac{\partial^\mu (\varphi_F - \text{id})}{\partial y^l \partial p^i \partial q^j} \right\|_{\mathcal{D}^{2\alpha}} \leq \uparrow D_\mu X_F \uparrow_{\mathcal{D}^\alpha} \uparrow D\varphi_F \uparrow_{\mathcal{D}^{2\alpha}}^\mu + \uparrow D_{\mu-1} X_F \uparrow_{\mathcal{D}^\alpha} s^\sigma + \uparrow DX_F \uparrow_{\mathcal{D}^\alpha} \|\partial^\mu \varphi_F\|_{\mathcal{D}^{2\alpha}}.$$

Here $\partial^\mu \varphi_F$ denote partial derivatives of order μ that do not differentiate with respect to x ; those that do have been included in the second term. It follows that

$$\left\| \frac{\partial^\mu (\varphi_F - \text{id})}{\partial y^l \partial p^i \partial q^j} \right\|_{\mathcal{D}^{2\alpha}} \leq \frac{2^\mu + \tilde{c}}{1 - cs^\sigma} s^\sigma$$

for sufficiently small s_0 .

QED

6.1.3. Transformation of $\tilde{N}$ into normal form. So far we have solved the small divisor problem (6.3) to construct a symplectic change of variables φ_F that transforms away the x -dependence of the lower order terms entering $\tilde{N}$. The second part of the iteration step consists of finding a symplectic change of variables $\phi_1 \circ \phi_2$ which transforms $\tilde{N}$ of (6.13) into the normal form (1.4) up to some small terms, i.e. $\tilde{N} \circ \phi_1 \circ \phi_2 = N_+ + O(\varepsilon_+)$.

Since $\tilde{N}$ and N_+ do not depend on the angular variables $x \in \mathbb{T}^n$, their flows leave the conjugate actions $y \in \mathbb{R}^n$ fixed and define two one degree of freedom systems in the remaining variables p and q . As shown in Broer *et al* (1993, 1995) one can apply the machinery of (planar) singularity theory to solve normalization problems (like the passage from $\tilde{N}$ to N_+) in one degree of freedom. In fact, we do not have to rely on this heavy machinery but can derive the necessary transformations ϕ_1 and ϕ_2 in an explicit way.

First we use the shear transformation

$$\phi_1 : \begin{cases} q_1 = q \\ p_1 = p + (a + 2P_{00200})^{-1} \sum_{j=0}^{[d/2]} Q_j(\lambda) q^j \end{cases} \quad (6.17)$$

to kill the crossing terms $\sum_{j=0}^{[d/2]} Q_j(\lambda) p q^j$ in $\tilde{N}$ (see (6.13)). We obtain

$$\begin{aligned} \tilde{N} \circ \phi_1 &= (\omega_+ | y) + \frac{a_+}{2} p_1^2 + \frac{b_+}{d!} q_1^d + P_{d-1}(\lambda) q_1^{d-1} + \sum_{j=1}^{d-2} \left(\frac{\lambda_j}{j!} + P_j(\lambda) \right) q_1^j \\ &\quad - \frac{1}{2a_+} \left(\sum_j Q_j(\lambda) q_1^j \right)^2 =: \tilde{N} - \frac{1}{2a_+} \left(\sum_j Q_j(\lambda) q_1^j \right)^2 \end{aligned} \quad (6.18)$$

with $\omega_+ = \omega + P_{01000}$, $a_+ = a + 2P_{00200}$ and $b_+ = b + d!P_{000d0}$.

Remark 6.11. The squared sum in (6.18) can be estimated by $(\varepsilon/s^d)^2 = s^{2d+2\sigma}$ and can therefore be included in the new perturbation.

The remaining term, $P_{d-1}(\lambda)q_1^{d-1}$, of weighted order $2d-2$ in the part $\tilde{N}$ of (6.18) can be dealt with by the standard translation

$$\phi_2 : \begin{cases} q_2 = q_1 + \frac{(d-1)!}{b_+} P_{d-1}(\lambda), \\ p_2 = p_1, \end{cases} \quad (6.19)$$

which is well-known from singularity theory (or algebra). We arrive at

$$\begin{aligned} \tilde{N} \circ \phi_1 \circ \phi_2 &= (\omega_+ | y) + \frac{a_+}{2} p_2^2 + \frac{b_+}{d!} q_2^d + \sum_{j=1}^{d-2} \frac{\lambda_j^+}{j!} q_2^j - \frac{1}{2a_+} \left(\sum_j Q_j(\lambda) q_1^j \right)^2 \circ \phi_2 \\ &= N_+ - \frac{1}{2a_+} \left(\sum_j Q_j(\lambda) q_1^j \right)^2 \circ \phi_2 \end{aligned}$$

with

$$\begin{aligned} \lambda_i^+ &= \lambda_i + i! P_i(\lambda) + \frac{(-1)^{d-i+1} (d-i-1)}{(d-i)! b_+^{d-i-1}} ((d-1)! P_{d-1}(\lambda))^{d-i} \\ &\quad + \sum_{j=i+1}^{d-2} \frac{(-1)^{j-i}}{(j-i)! b_+^{j-i}} ((d-1)! P_{d-1}(\lambda))^{j-i} (\lambda_j + j! P_j(\lambda)). \end{aligned}$$

Recall that we always ignore constant terms. Since the Jacobian of $\lambda \mapsto \lambda^+$ is non-singular, we can replace λ by λ^+ in the next KAM-step. Thus we get the desired new normal form.

6.1.4. Estimates of the iteration step. We now compose our map $\Psi : \mathcal{D}_+ \rightarrow \mathcal{D}$ using $\mathcal{D}_+ \subseteq \mathcal{D}^{4\alpha}$ and $\mathcal{D}^\alpha \subseteq \mathcal{D}$. We have already remarked that $\varphi_F : \mathcal{D}^{2\alpha} \rightarrow \mathcal{D}^\alpha$. The inequalities

$$\begin{aligned} |P_{01000}|_U &\leq \frac{\varepsilon}{s^{2d}} < \frac{\beta}{12}, \\ \left| a_+^{-1} \sum_j Q_j(\lambda) q^j \right| &\leq \frac{\varepsilon}{s^d} < \frac{(\alpha s)^d}{4}, \end{aligned}$$

imply $\phi_1 : \mathcal{D}^{3\alpha} \rightarrow \mathcal{D}^{2\alpha}$, where we have subsumed $\omega \mapsto \omega_+$ into this mapping. Similarly we subsume $\lambda \mapsto \lambda^+$ into ϕ_2 and obtain $\phi_2 : \mathcal{D}^{4\alpha} \rightarrow \mathcal{D}^{3\alpha}$ from

$$\begin{aligned} |(d-1)! b_+^{-1} P_{d-1}(\lambda)| &\leq s^{2\sigma+2} < \frac{(\alpha s)^2}{8}, \\ |i! P_i(\lambda)| &\leq \frac{\varepsilon}{s^{2i}} < \frac{(\alpha s)^{2d-2i}}{8}. \end{aligned}$$

Together we have that

$$\Psi = \varphi_F \circ \phi_1 \circ \phi_2 : \mathcal{D}^{4\alpha} \rightarrow \mathcal{D}^\alpha.$$

This defines the desired coordinate transformation for one iteration step. As in lemma 6.10, we have the estimates for Ψ .

Lemma 6.12. For any given l, i, j there is a constant s_0 , depending only on n, τ and $|l| + i + j$, such that if $s \leq s_0$

$$\|\Psi - \text{id}\|_{C^{lij}(\mathcal{D}^{4\alpha})} \leq s^\sigma.$$

Proof. Note that ϕ_1 and ϕ_2 are linear maps, i.e.

$$D^\mu \Psi = D^\mu \varphi_F \circ \phi_1 \circ \phi_2 \bullet \underbrace{(\phi_1 \circ \phi_2, \dots, \phi_1 \circ \phi_2)}_{\mu \text{ entries}}.$$

The estimate follows by lemma 6.10, the chain rule and the inductive principle. QED

The new perturbation is

$$P_+ = \bar{P} \circ \phi_1 \circ \phi_2 + \left\{ N_0, \sum_{\substack{0 < |k| \leq K \\ d+2 < m \leq 2d}} F_{km} e^{i(k|x)} \right\} \circ \phi_1 \circ \phi_2 - \frac{1}{2a_+} \left(\sum_j \mathcal{Q}_j(\lambda) q^j \right)^2 \circ \phi_2, \quad (6.20)$$

where

$$\bar{P} = \{R, F\} + \int_0^1 (1-t) \{ \{N+R, F\}, F \} \circ \varphi_t^F dt + (P-R) \circ \varphi_F$$

was defined in (6.1). We have to estimate all terms by $\varepsilon_+ = s^\kappa \varepsilon$. Using the Cauchy inequality we immediately have

$$\begin{aligned} |\{R, F\} \circ \phi_1 \circ \phi_2|_{\mathcal{D}^{4\alpha}} &\leq |\{R, F\}|_{\mathcal{D}^{2\alpha}} \\ &\leq s^{-2d} |R|_{\mathcal{D}^7} |F|_{\mathcal{D}^7} \\ &\leq s^{2d+2\sigma} \end{aligned}$$

and

$$\begin{aligned} \left| \int_0^1 (1-t) \{ \{N+R, F\}, F \} \circ \varphi_t^F dt \right|_{\mathcal{D}^{2\alpha}} &\leq |\{N+R, F\}, F|_{\mathcal{D}^\alpha} \cdot \int_0^1 (1-t) dt \\ &\leq s^{-2d} |\{N+R, F\}|_{\mathcal{D}^7} |F|_{\mathcal{D}^7} \\ &\leq s^{-2d} |F|_{\mathcal{D}^6}^2 \\ &\leq s^{2d+2\sigma}. \end{aligned}$$

Furthermore, (6.12) yields

$$|(P-R) \circ \varphi_F \circ \phi_1 \circ \phi_2|_{\mathcal{D}^{4\alpha}} \leq \alpha^{1-\sigma} s^\kappa \varepsilon.$$

We have already remarked that

$$\left| \frac{1}{2a_+} \left(\sum_{j=0}^{[d/2]} \mathcal{Q}_j(\lambda) q^j \right)^2 \right|_{\mathcal{D}^{3\alpha}} \leq s^{\sigma-\kappa} s^\kappa \varepsilon$$

and finally we obtain

$$\left| \left\{ N_0, \sum_{\substack{0 < |k| \leq K \\ d+2 < m \leq 2d}} F_{km} e^{i(k|x)} \right\} \right|_{\mathcal{D}^{2\alpha}} \leq s^{d-2} \left| \sum_{\substack{0 < |k| \leq K \\ d+2 < m \leq 2d}} F_{km} e^{i(k|x)} \right|_{\mathcal{D}^7} \leq s^{d-2} \varepsilon.$$

In total, we get

$$|P_+|_{\mathcal{D}_+} \leq |P_+|_{\mathcal{D}^{4\alpha}} \leq c \alpha^{(1-\sigma)(\sigma-\kappa)} s^\kappa \varepsilon < \varepsilon_+,$$

where we used $\alpha^{(1-\sigma)(\sigma-\kappa)}$ to absorb the accumulated constant c . Moreover, as the domain $\mathcal{D}_+$ is again smaller than $\mathcal{D}^{4\alpha}$, we have for $m := \|(l, i, j, h)\| \leq 2d$

$$\left| \frac{\partial^{|l|+i+j+h|} P_+}{\partial y^l \partial p^i \partial q^j \partial \lambda^h} \right|_{\mathcal{D}_+} \leq s_+^{-m} \varepsilon_+$$

by Cauchy's inequality. This concludes the proof of lemma 6.1.

Remark 6.13. The latter inequality will be used to prove that all the coefficients of P_∞ with weighted order less than $2d$ vanish.

6.2. Iteration and convergence

In the previous subsection we were concerned with one step of the iteration process. Thus, given a small perturbation $H_v = N_v + P_v$ of our normal form N_v , we now know how to construct a coordinate change Ψ_v such that $H_{v+1} := H_v \circ \Psi_v$ is an even smaller perturbation of the adapted normal form N_{v+1} . Our next aim is to show that this process ‘converges’, leading to a well-defined limit $H_\infty = N_\infty + P_\infty$ where the perturbing term P_∞ no longer forms an obstruction for the desired conclusions.

By composition, $\Phi_{v+1} := \Psi_0 \circ \Psi_1 \circ \cdots \circ \Psi_v$, we obtain a coordinate transformation that turns the given $H_0 = N_0 + P_0$ into $N_{v+1} + P_{v+1}$. Our aim is to find a ‘limit’ Φ_∞ with

$$H_0 \circ \Phi_\infty = N_\infty + P_\infty.$$

The occurrence of P_∞ reflects the fact that $\lim_{v \rightarrow \infty} \Phi_v$ is only defined on

$$\bigcap \mathcal{D}_v = U_{r_0/2}(\mathbb{T}^n) \times \{0\} \times \{0\} \times \{0\} \times \mathcal{O}'_1.$$

To obtain the desired convergence we will need a bound on the C^μ -norm,

$$\|\Phi_v\|_{C^\mu(\mathcal{D}_v)} = \max_{|l|+i+j \leq \mu} \left\| \frac{\partial^{|l|+i+j} \Phi_v}{\partial y^l \partial p^i \partial q^j} \right\|_{\mathcal{D}_v}.$$

Lemma 6.14. *A constant $c > 0$ exists, depending only on n, τ, d and μ , such that*

$$\|\Phi_v\|_{C^\mu(\mathcal{D}_v^\mu)} \leq c \quad \text{for every } v \in \mathbb{N}.$$

Proof. Firstly, we note that the estimate in this lemma holds for $\Psi_v = \varphi_{F_v} \circ \phi_1^v \circ \phi_2^v$ by lemma 6.12. From $\Phi_{v+1} = \Phi_v \circ \Psi_v$ it follows that $(\partial/\partial z)\Phi_{v+1} = ((\partial/\partial z)\Phi_v \circ \Psi_v) \bullet D\Psi_v$ and we have to estimate products of the form

$$\left(\frac{\partial^{|l|+i+j} \Phi_v}{\partial y^l \partial p^i \partial q^j} \circ \Psi_v \right) \bullet (D^{\ell_1} \Psi_v, \dots, D^{\ell_\ell} \Psi_v)$$

with $\ell = |l| + i + j$. The estimates for Φ_v can be proven inductively. qed

In the case of, e.g., normally elliptic tori the transformations one works with form a group (cf Pöschel (1989)). This allows concentration on the coefficient functions and to use the limits of these coefficient functions to define the desired limit transformation. However, in the present situation the coordinate changes Ψ_v do not form a group. Indeed, the bifurcating tori require higher order terms, which in turn have to be dealt with by both the Hamiltonian F_v that generates the first part, φ_{F_v} , of the coordinate transformation Ψ_v and by its second part, defined explicitly in (6.17) and (6.19). The problem is now that one cannot restrict oneself to the fixed weighted order $2d$ in $(y, p, q; \lambda)$ imposed by the type of bifurcation, as the composition of Ψ_v and Ψ_{v+1} itself would increase this order to $4d$. Therefore, we have to pass to a polynomial truncation of fixed degree in order to define Φ_∞ by means of limits of coefficient functions. This truncation has to satisfy the following conditions.

- (i) We do not want to destroy the symplectic structure, i.e. the ‘truncated transformations’ Υ_v have to be symplecto-morphisms as well.
- (ii) The estimates implied by lemma 6.1 should remain valid after the transformed Hamiltonian functions $H_0 \circ \Phi_v$ are replaced by the Hamiltonians $H_0 \circ \Upsilon_v$.

In view of the first condition we do not simply truncate Φ_v , but truncate a generating function to define Υ_v as follows. Since $\Phi_v : (x, y, p, q; \lambda, \omega) \mapsto (X, Y, P, Q)$ is a symplecto-morphism for fixed (λ, ω) , the 1-form

$$\sum_{i=1}^n (y_i - Y_i) dx_i + (X_i - x_i) dY_i + (Q - q) dP + (p - P) dq \quad (6.21)$$

is closed and can therefore be written as dS_v . Indeed, being composed from finitely many translations ϕ_2^μ , shear transformations ϕ_1^μ and time one maps ϕ_F^μ , the transformation Φ_v is homotopic to the identity. Thus, the closed one-form (6.21) is exact, i.e. S_v is one-valued. The function $S_v = S_v(x, Y, P, q)$ is a generating function for Φ_v (cf Arnol'd (1978)). Note that S_v itself is only determined up to a constant and that all partial derivatives are 2π -periodic in the toral coordinates $x_1, \dots, x_n$.

Because of the second condition we define the truncation $\tilde{S}_v$ of S_v to be of order $d+1$ in $(Y, P, q; \lambda)$. Furthermore, we drop all terms that involve more than one derivative with respect to parameters λ_j . On the other hand we do not truncate in x or ω .

To be precise, we write

$$\Phi_v(x, y, p, q; \lambda, \omega) = ((x, y, p, q) + W_v(x, y, p, q; \lambda, \omega); \lambda + \tilde{\Lambda}_v(\lambda, \omega), \omega + \tilde{\Omega}_v(\lambda, \omega))$$

and let $\mathcal{F}_v : \mathcal{D}_v \rightarrow \mathcal{D}_0$ denote the transformation of $(x, y, p, q; \lambda, \omega)$ into

$$(x, y + W_v^2(x, y, p, q; \lambda, \omega), p + W_v^3(x, y, p, q; \lambda, \omega), q; \lambda, \omega) \stackrel{!}{=} (x, Y, P, q; \lambda, \omega)$$

and $\mathcal{G}_v := \mathcal{F}_v^{-1}$. The truncations $\tilde{S}_v$ are polynomials in Y, P, q and λ , the coefficients of which are holomorphic functions in x and ω . To truncate we write S_v as a Taylor series at $\mathcal{F}_v(x, 0, 0, 0; 0, \omega) =: (x, Y_v, P_v, 0; 0, \omega)$. Therefore,

$$S_v^{lijh}(x, \omega) = \frac{\partial^{|l|+|i|+|j|+|h|} S_v}{\partial Y^l \partial P^i \partial q^j \partial \lambda^h}(x, Y_v, P_v, 0; 0, \omega),$$

and we define

$$\tilde{S}_v(x, y, p, q; \lambda, \omega) := \sum_{|l|+|i|+|j|=0}^{d+1} \sum_{|h|=0}^{\min(|l|+|i|+|j|, 1)} S_v^{lijh}(x, \omega) \cdot (Y - Y_v)^l (P - P_v)^i q^j \lambda^h.$$

Lemma 6.15. *Under the conditions of lemma 6.1 the sequence $(\tilde{S}_v)_{v \in \mathbb{N}}$ of truncations is uniformly convergent on $\overline{U_{r_0/2}(\mathbb{T}^n)} \times \mathcal{O}'_1$.*

Proof. For $i \geq 1$ we can use $\partial S_v / \partial P = W_v^4 \circ \mathcal{G}_v$. We immediately get

$$\begin{aligned} |S_{v+1}^{0100}(x, \omega) - S_v^{0100}(x, \omega)| &= |W_{v+1}^4(x, 0, 0, 0; 0, \omega) - W_v^4(x, 0, 0, 0; 0, \omega)| \\ &\leq \|\Phi_v\|_{C^2(\mathcal{D}_v)} |(\Psi_v - \text{id})(x, 0, 0, 0; 0, \omega)| \leq s_v^\sigma \end{aligned}$$

and this exponential decay yields a limit $\tilde{S}_\infty^{0100}$. For higher derivatives we use the chain rule to write $S_v^{lijh}(x, \omega)$ as a sum of terms

$$\left(\frac{\partial^\mu W_v^4}{\partial y^{l'} \partial p^{i'} \partial q^{j'} \partial \lambda^{h'}} \circ \mathcal{G}_v \right) (D^{l_1} \mathcal{G}_v, \dots, D^{l_\mu} \mathcal{G}_v)$$

with $(l', i', j', h') \leq (l, i, j, h)$ in all components and $\iota_1 + \dots + \iota_\mu = |l| + |i| + |j| - 1$. Using $D\mathcal{G}_{v+1} - D\mathcal{G}_v = D\mathcal{G}_v(D\mathcal{F}_v - D\mathcal{F}_{v+1})D\mathcal{G}_{v+1}$, we obtain again an exponential decay for the difference $S_{v+1}^{lijh}(x, \omega) - S_v^{lijh}(x, \omega)$ and thus a limit coefficient function $\tilde{S}_\infty^{lijh}(x, \omega)$.

By means of $\partial S_v / \partial Y = W_v^1 \circ \mathcal{G}_v$ and $\partial S_v / \partial q = -W_v^3 \circ \mathcal{G}_v$ we obtain this same result for $|l| \geq 1$ and $j \geq 1$ as well.

We are left with the coefficient functions $S_v^{000h}(x, \omega)$. Their averages vanish and they are determined by $\partial S_v / \partial x = -W_v^2 \circ \mathcal{G}_v$. We conclude

$$\begin{aligned} |S_{v+1}^{0000}(x, \omega) - S_v^{0000}(x, \omega)| &\leq \max_{i=1, \dots, n} \left| \int_0^{x_i} W_v^{2,i} - W_v^{2,i} \circ \mathcal{G}_v \, d\tilde{x}_i \right| \\ &\leq |W_v^2 - W_v^2 \circ \mathcal{G}_v| \leq s_v^\sigma \end{aligned}$$

and similarly for S_v^{000h} with $|h| = 1$.

QED

Instead of investigating $\Phi_\infty = \lim_{v \rightarrow \infty} \Upsilon_v$ directly, we work with the (truncated) generating functions $\tilde{S}_v$. Using the inverse approximation lemma (cf Zehnder (1975)), we obtain Whitney- C^∞ -smooth limit functions $\tilde{S}_\infty^{lijh}$ on $\overline{U_{r_0/2}(\mathbb{T}^n)} \times \mathcal{O}'_1$. They constitute the coefficients of a generating function

$$\tilde{S}_\infty : U_{r_0/2}(\mathbb{T}^n) \times \mathbb{C}^n \times \mathbb{C}^2 \times \mathbb{C}^{d-2} \times \mathcal{O}'_1 \longrightarrow \mathbb{C},$$

which is analytic in x, Y, P, q and λ . With Whitney's extension theorem (cf Whitney (1934)), we get $\tilde{S}_\infty(x, Y, P, q; \lambda, \omega)$ for all $\omega \in \mathbb{R}^n$. This defines for every (λ, ω) a symplecto-morphism on $\mathbb{T}^n \times \mathbb{R}^n \times \mathbb{R}^2$. To obtain Φ_∞ we have to complete these symplecto-morphisms by $\text{id} + (\tilde{\Lambda}_\infty, \tilde{\Omega}_\infty) = \text{id} + \lim_{v \rightarrow \infty} (\tilde{\Lambda}_v, \tilde{\Omega}_v)$. This latter convergence to Whitney- C^∞ -smooth functions is an immediate consequence of lemma 6.14 and the inverse approximation lemma.

To conclude the proof of theorem 2.1 (with $\gamma = 1$) we apply the inverse approximation lemma to the coefficient functions a_v, b_v of the normal forms N_v and obtain a Whitney- C^∞ -smooth Hamiltonian function N_∞ which is (again) analytic in y, p, q and λ . Letting $P_\infty := H_0 \circ \Phi_\infty - N_\infty$ we have, according to our choice of the truncations $\tilde{S}_v$ of S_v at order $d+1$,

$$P_{\infty, lijh} = \lim_{v \rightarrow \infty} P_{v, lijh}$$

as long as $|h| \leq 1$ and $|l| + i + j \leq d$. In particular we can conclude that these all vanish for weighted order $\|(l, i, j, h)\| \leq 2d$. This concludes the proof of theorem 2.1 (with $\gamma = 1$).

Remark 6.16. While the normal form (1.4) comes from singularity theory, the above proof does not use the preparation theorem (the main tool for dealing with universal unfoldings of singularities (cf Bröcker and Lander (1975))). Indeed, we could use the explicit transformations (6.17) and (6.19) to get rid of some lower order terms, whereas occurring higher order terms were included in the new perturbation (6.20) of the KAM iteration scheme. Note that both the preparation theorem and KAM theory ultimately rely on the implicit mapping theorem.

6.3. Scaling properties

The final step in our proof of theorem 2.1 consists in re-installing the Diophantine constant, γ , by means of a suitable scaling. The scaling properties of theorem 2.1 with respect to γ are also important in applications. While γ will always be chosen as small as the perturbation allows, one often has to choose γ as a function of occurring parameters that for certain values force $\gamma \searrow 0$. Therefore, we address this question in a slightly more general fashion and consider the coordinate transformation

$$(x, y, p, q; \lambda, \omega) \mapsto (X, Y, P, Q; \Lambda, \Omega)$$

with

$$\begin{aligned} X &= x, \\ \Omega &= \gamma^{-1} \omega \end{aligned}$$

and, using $\Gamma = \gamma^\varsigma$ with a fixed exponent ς that may be specified later on,

$$\begin{aligned} Y &= \Gamma^{-2d+1} y, \\ P &= \Gamma^{-d} p, \\ Q &= \Gamma^{-2} q, \\ \Lambda_j &= \Gamma^{-2d+2j} \lambda_j. \end{aligned}$$

In the new coordinates the normal form (1.4) becomes

$$\gamma^{2d\varsigma+(1-\varsigma)} \hat{N}(X, Y, P, Q; \Lambda, \Omega),$$

where the coefficient functions $\hat{a}$ and $\hat{b}$ of $\hat{N}$ are related to those of N through

$$\begin{aligned} \hat{a}(\Omega) &= \gamma^{\varsigma-1} a(\gamma\Omega), \\ \hat{b}(\Omega) &= \gamma^{\varsigma-1} b(\gamma\Omega). \end{aligned}$$

For $\varsigma = 1$ this yields the desired re-installation of the Diophantine constant, γ .

As already remarked in section 3.1, perturbations of superintegrable systems lead to dynamics with two time scales: superposed on the fast unperturbed quasi-periodic motion one has a slow movement of, e.g., the angular momentum in the rigid body example of section 3.1. The slow dynamics is induced by the perturbation and may involve a bifurcation scenario, with fast dynamics on the invariant tori. The coefficient functions a and b of a normal form (1.4) would then be small as well, i.e. of the order δ of the perturbation. However, this can easily be remedied through a scaling with $\varsigma = 1/(2d-1)$, leading to coefficient functions $\hat{a}$ and $\hat{b}$ that do satisfy the necessary estimates from below. In this process we end up with a very small Diophantine constant $\gamma \sim \delta^{1+1/(2d-2)}$, expressing the well-known fact that many more invariant tori become Diophantine in systems with two time scales.

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