Spin injection, accumulation, and precession in a mesoscopic nonmagnetic metal island

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We experimentally study spin accumulation in an aluminum island with all dimensions smaller than the spin-relaxation length, so that the spin imbalance throughout the island is uniform. Electrical injection and detection of the spin accumulation are carried out in a four-terminal geometry by means of four cobalt electrodes connected to the island through tunnel barriers. We model the system theoretically and we investigate the role of the ferromagnetic electrodes on the spin accumulation at the limit at which the electron diffusion time can be neglected. We present measurements of spin accumulation at room temperature and at 4.2 K: in both cases the spin accumulation signal is larger than the Ohmic resistance of the aluminum island.

From magnetization precession measurements at room temperature, we extract a spin-relaxation time \( \tau_{sf} = 60 \text{ ps} \) and a polarization \( P = 8\% \) for tunnel barriers with resistances as low as \( 20 \Omega \mu \text{m}^2 \). We show that the precession measurements are invariant under the interchange of voltage and current electrodes, and under the reversal of magnetic fields and magnetizations, according to the reciprocity theorem. We show that spin accumulation and spin precession in a system with uniform magnetization can be described in terms of the (relative) orientation of the ferromagnetic contacts’ magnetizations and we determine from precession measurements the angles between the magnetization direction of the contacts.

I. INTRODUCTION

Creating and manipulating a nonequilibrium magnetization in a nonmagnetic metal is a central requirement in the field of spintronics.\textsuperscript{1} The orientation of an electron spin injected in a nonmagnetic metal is the result of the interaction of the spin intrinsic magnetic moment with the magnetic fields in which the spin is moving. In the presence of a uniform magnetic field, the spin precesses coherently around the field’s direction and its orientation changes with a uniform precession frequency.

In a diffusive, a (nonuniform) effective magnetic field arises from the relativistic motion of the spin in the electric field of the metal ions and the defects.\textsuperscript{2} This is called spin-orbit interaction and it is responsible for the randomization of the spin orientation: the relaxation of the nonequilibrium magnetization occurs by transferring the spin angular momentum to the metal lattice in a time scale in the order of 100 ps.

To induce a spin current and a spin accumulation, a spin-dependent scattering is required for the conduction electrons. The usual approach in all-electrical transport experiments is to drive a current from a ferromagnet (FM) whose band structure is spin dependent, to a nonmagnetic (NM) metal. It has been noted that the main obstacle for efficient spin injection in the diffusive regime is the short spin-relaxation length in the ferromagnet, a problem known by the name of conductance mismatch.\textsuperscript{3} In giant magnetoresistance (GMR) experiments,\textsuperscript{4} with vertical devices, the useful signal can be made large enough for practical applications by reducing the distance between the ferromagnetic layers. In lateral structures, this is not a feasible solution, due to technological limitations. Also, in the clean contact regime, measures have to be taken to ensure that either the current path is perpendicular to the FM/NM interface or that the voltage probes are separate from the current path. Anomalous magnetoresistance and Hall effect can mimic and hide the spin accumulation.\textsuperscript{3}

In order to overcome these problems, tunnel barriers were proposed\textsuperscript{3} at the interface between the ferromagnetic metal and the normal-metal layer (the tunnel barrier conductance being proportional to the FM density of states), thereby making the tunnel barrier the dominant (spin dependent) resistance of the system.

Previous experiments have studied the spin current in systems larger than the spin-relaxation length. A seminal experiment was performed by Johnson and Silsbee\textsuperscript{5} in the clean contact regime and four-terminal configuration, in a device with two lateral dimensions larger than the spin-relaxation length. The experiment was performed on single-crystal aluminum bar. The long spin-relaxation length they found, \( \lambda_{sf} = 50 \mu \text{m} \) at 4.2 K, allowed them to observe a weak (tens of pV) spin precession signal at macroscopic scale. In diffusive metallic systems, with typical relaxation lengths in the \( \mu \text{m} \) range, observations were done by Jedema and co-workers\textsuperscript{5,7} at room temperature in a one-dimensional device, both with clean contacts and with tunnel barriers at the FM/NM interfaces in four-terminal devices. The spin signal in the clean case was about 1 m\( \Omega \) and about two orders of magnitude larger for the devices with tunnel barriers, proving their efficiency as spin injector/detector. Spin accumulation occurs in two terminal pillar structures with all dimensions shorter than the spin-relaxation length, used to study the magnetization reversal of a thin FM layer, driven by a spin polarized current created by a second massive FM layer.\textsuperscript{8} The torque exerted on the FM layer is proportional to the spin accumulation, which is in the mV range.

Recently\textsuperscript{5} we have performed electrical injection and detection of spin accumulation in an aluminum island with all lateral dimensions shorter than the spin-relaxation length...
The description of coherent spin transport in a diffusive metal is obtained from the Boltzmann transport equation. The two-channel (spin up and spin down) model of Valet and Fert,\textsuperscript{10} which successfully describes the experimental results of giant magnetoresistance, is, however, limited to the collinear (magnetization either parallel or antiparallel) case. In the general case, one has to retain all the information about the spin direction inside the bulk metal and at the FM/NM interfaces.

A theoretical approach to systematically studying the transport through FM/NM interfaces in the noncollinear situation was developed by Brataas \textit{et al.}\textsuperscript{11} The relevant parameter, alongside the interface conductance for spin-up and spin-down electrons \( G^u, G^d \), is a (complex valued) mixing conductance term \( G^x \), describing the reflection of electron spins perpendicular to the magnetization of the ferromagnet. \( G^z \) is related to the amount of angular moment that the electron spin has transferred to the ferromagnet, and plays an important role in the description of the spin torque and spin pumping.\textsuperscript{12,13}

Here we present a systematic study of noncollinear spin accumulation in a small metallic island, extending the results of Ref. 9. Theoretically, we apply the circuit theory to the system and show how the presence of the FM contacts provides an additional (and anisotropic) mechanism for the relaxation of the spin accumulation, with the relaxation occurring at a faster rate in the direction perpendicular to the FM magnetization axis.

In Sec. II, we derive a formula in the zero-dimensional limit (\( \tau_{\text{diff}} \ll \tau_f \)) for the spin accumulation as a function of the contacts properties. Section III describes the sample fabrication and Sec. IV is a short summary of the relevant theory. The geometry of the sample and the measuring configurations are described in Sec. V.

Section VI presents an extensive set of measurements of spin accumulation in a nonmagnetic island at 4.2 K and at room temperature (RT). We use spin precession as a tool to analyze the spin accumulation and extract the relevant parameters such as the spin-relaxation time, and the direction of the magnetization of the FM contacts. We also show that, for our device, the magnetization relaxation is independent of the mixing conductance term.

II. THEORY

To completely characterize the electronic transport in the linear regime, including the spin, four chemical potentials are necessary, one spin independent (charge) and three spin dependent (magnetization). The main idea of the finite element theory of Brataas \textit{et al.}\textsuperscript{11} is to divide the system into (normal or ferromagnetic) nodes connected to each other or to reservoirs by contacts (interfaces). A contact can be spin selective, that is, it can have different conductances for the two spin populations.

In each node, spin accumulation appears as a result of the spin currents through the contacts. In turn, the amount of spin current through each contact is determined by its conductance and by the chemical potentials of the two nodes on each side of the contact.

Thus the problem of the transport in the system is broken down into the solution of the motion of charge and magnetization inside a node with the additional boundary conditions given by the charge and spin current through the contacts. The finite element theory of Brataas \textit{et al.} provides an elegant way to describe the charge and spin currents through FM/NM interfaces.

In the following, we will briefly review the elements of the theory that are relevant for our experimental situation. We will then present an analytical solution for the situation in which the electron diffusion time inside the island \( \tau_{\text{diff}} \) can be neglected when compared to the spin-relaxation time \( \tau_f \). This last assumption is equivalent to saying that the distribution of magnetization is uniform in the island and we will therefore call it a zero-dimensional system from here on.

In a FM/NM device, and for arbitrary configuration of the magnetic reservoirs, a spin current injected from a FM reservoir to a node of normal metal will cause a nonequilibrium accumulation of magnetization. In the linear regime, we describe the transport properties by means of four chemical potentials \( \mu(x), \mu(x), \mu(x), \mu(x) \), where \( \mu(x) = \int f(x) e \, dx \) and \( \mu = \int f(x) e \, dx \) are the spin-independent and spin-dependent chemical potentials in the node and \( f(x) \) and \( f(x) \) are the spin-independent and spin-dependent distribution functions. \( \mu = (\mu_s, \mu_s, \mu_s) \) represents the spin accumulation in different directions and \( |\mu| \) its magnitude. In equilibrium, no spin accumulation exists in normal and ferromagnetic nodes or reservoirs.

Only in the particular case in which the spin accumulation has the same direction throughout the entire system (and the contacts are all collinear), one can use a description in terms of two, spin-up and spin-down, chemical potentials: these are related to \( \mu, \mu \) by \( \mu = \mu + |\mu| \) and \( \mu = \mu - |\mu| \).

In a reservoir, the spin-independent chemical potential is set by the applied bias voltage \( eV \).

In the experimental device, see Fig. 1, the node is an aluminum island \( 400 \times 400 \times 30 \) nm, the four cobalt electrodes act as reservoirs, and the AlOx tunnel barriers at the aluminum/cobalt interface are the contacts. The motion of charge and magnetization in the island is diffusive as the mean free path is of the order of 5 nm at RT and 20 nm at 4.2 K.

The finite element theory specifies the charge and spin particle currents \( i \) and \( i \) through the contacts that connect the island. This is related to the amplitude probabilities \( r_{mn}^e \) for the reflection of a spin up electron from mode \( m \) to mode \( n \) in the normal metal, evaluated at the normal side of the contact. If, as in our case, the tunnel barrier is nonmagnetic and \( \mathbf{m} \), is the unit vector representing the magnetization direction of the \( j \) electrode, the natural choice for the quantization axis is collinear to \( \mathbf{m} \) (and \( \mathbf{m} \) means, for instance, parallel to \( \mathbf{m} \))
\[ e^2 i_j = G_j (\mu^F_j - \mu) - P_j G_j (\mathbf{m}_j \cdot \mu - |\mu^F_j|) \quad (1) \]

and the spin current

\[ e^2 i_j = P_j G_j (\mu^F_j - \mu) \mathbf{m}_j + G_j [\mu^F_j - (\mathbf{m}_j \cdot \mu) \mathbf{m}_j] + 2 \Re G_j^{|} \mathbf{m}_j \times (\mathbf{m}_j \times \mu) - 2 \Im G_j^{|} \mathbf{m}_j \times \mu, \quad (2) \]

\( \mu^F_j \) being the spin-independent chemical potential of the FM electrode \( j \). The conductances are defined according to the Landauer-Büttiker formalism:

\[ G^{|} = \frac{e^2}{h} [M - \sum_{nm} |r_{nm}|^2] \quad (3) \]

for the spin-up conductance and for the mixing conductance \( G^{|} \),

\[ G^{|} = \frac{e^2}{h} [M - \sum_{nm} r_{nm}(r_{nm})^\ast], \quad (4) \]

where \( M \) is the total number of modes. The spin mixing conductance affects only the component of the spin accumulation perpendicular to the the electrode’s magnetization by rotating the spins around it; see the last two terms of Eq. (2). The validity of the above expressions is restricted to the case in which the contacts limit the total conductance.\(^{16} \)

In our experiment, we use FM electrodes both for the injection of a spin polarized current and for the detection of the spin accumulation. We now derive from the circuit theory some relationships relevant in the two cases: a FM electrode as a voltage probe and a FM electrode as a spin source.

When a FM electrode is used as a voltage probe, the spin-independent chemical potential on the FM side is raised above the NM chemical potential by an amount that depends on the spin accumulation on the two sides of the contact. To see this, we set \( i = 0 \) in Eq. (1) and obtain

\[ \mu^F_j = \mu + P_j (\mathbf{m}_j \cdot \mu - |\mu^F_j|), \quad (5) \]

\( P_j \) being the “efficiency” of the detector.

When the FM electrode is used as a spin injector, the charge current carries along a spin current. We use Eq. (1) in Eq. (2), as we control in our experiment the charge current, and we find an expression relating \( i_j(x) \) and \( i_j(x) \):

\[ e^2 i_j(x) = P_j e^2 i_j x, m_j + G_j (1 - P_j^2) [(\mu^F_j - (\mathbf{m}_j \cdot \mu) \mathbf{m}_j] - 2 \Im G_j^{|} \mathbf{m}_j \times (\mathbf{m}_j \times \mu) + 2 \Re G_j^{|} \mathbf{m}_j \times (\mathbf{m}_j \times \mu), \quad (6) \]
The first term shows that a charge current \( I = eI \) carries a spin current \( \mathbf{I} = \mu_b \mathbf{J} \), \( \mu_B \) being the Bohr’s magneton, with an efficiency given by the polarization \( P \) of the interface. The second term describes a decrease in conductance because one spin channel is partially blocked.

If the contacts have much higher resistance than the ferromagnetic region in which spin accumulation occurs, the particle currents are thus determined by the large voltage drop across the interface and the small spin accumulation in the ferromagnet can be neglected altogether, \( \mu^T = 0 \). This is valid in the limit \( G \ll \sigma_p \lambda_F^3 \) (in the order of ohms for thin FM layers), where \( \sigma_p \) and \( \lambda_F \approx 50 \text{ nm} \) are, respectively, the conductivity and the spin-relaxation length of the ferromagnet.

For the spin-independent chemical potential, one has to solve the diffusion equation

\[-D \nabla^2 \mu = 0\]

with the boundary condition set by the charge current (its direction is along the gradient of the chemical potential)

\[ i_j(x) = v_D D |\nabla \mu_j|, \]

For the spin-dependent chemical potential, in the limit \( \tau_{\text{diff}} \ll \tau_{sf} \), one can neglect the diffusion term \(-D \nabla^2 \mu\) and assume a uniform spin accumulation \( \mu_a \) throughout the island. In the steady state, the injection of magnetization has to compensate for the relaxation:

\[
\frac{1}{v_D} \sum_j \frac{\mu_a}{\tau_{sf}} - \frac{g \mu_B}{\hbar} \mathbf{B} \times \mu_a,
\]

where the first term on the right-hand side describes spin relaxation and the second spin precession in a uniform external magnetic field.\(^{17}\) Using the expression for the spin current, Eq. (6), we rearrange the terms, to show that the presence of the contacts introduces an extra mechanism for spin relaxation.

The spin-dependent chemical potential can be written in the following form:\(^{18}\)

\[
T \mu_a = \frac{1}{v_D} \sum_j P_{ji} \mathbf{m}_j = \mathbf{v},
\]

where the term on the right-hand side is the source term \( \mathbf{v} \) and \( T \) is a 3 × 3 matrix operator.

An explanation of the above now follows. The first term proportional to \( \mu_a \) relaxes the magnetization via two different mechanisms: (a) the interaction of the spin with the normal metal (spin-orbit scattering), occurring at a rate \( \tau_{sf}^{-1} \), and (b) the leaking of the spins to the leads, proportional to the interfaces’ conductance, \( G_j \). The time associated with the latter is the spin escape time \( \tau_{\text{esc}} = \sum_j G_j (1 - P_j^2)/v_D e^2 \). The total spin-relaxation time is the sum of the two contributions: \( \tau_{rel} = \tau_{sf}^{-1} + \tau_{\text{esc}}^{-1} \).

This time scale \( \tau_{\text{esc}} \) is relevant in a two-terminal GMR-type of measurement: a spin-dependent resistance appears if electrons cross the second FM/NM interface while still retaining the information about the magnetization of the first FM/NM interface. This is equivalent to having \( \tau_{sf} > \tau_{\text{esc}} \).

The second term plays the role of an effective magnetic field \( \mathbf{a} = g \mu_B \mathbf{B} / \hbar + \mathbf{a}_{\text{mix}} \); the magnetization perpendiccular to \( \mathbf{a} \) precesses with constant Larmor frequency \( f \) around it. The presence of the leads introduces an extra term \( \mathbf{a}_{\text{mix}} \), that depends on the orientation of the contacts and changes sign if all the magnetizations \( \mathbf{m} \) are reversed.

The last term affects only the spin accumulation perpendicular to \( \mathbf{m} \). If this is the case, it simply becomes proportional to \( \mu_a \) and it adds up to the spin relaxation. In other words, it is responsible for the anisotropic relaxation of the magnetization.

It was shown\(^11\) that the coefficients \( c_j = 2 \mathbf{J} G_j \) and \( G_j (1 - P_j^2)/v_D e^2 \) are larger than 0, resulting in an enhancement of the relaxation of the component perpendicular to the electrodes’ magnetization. This follows from the assumption that in the FM, the spin accumulation is only collinear to the electrode’s magnetization. \( c_j \) has the units of time and represents the spin mixing time \( \tau_{\text{mix}} \).

Equation (10) can be solved by inverting the matrix \( T \), giving for \( \mu_a \)

\[
\begin{align*}
\mathbf{a}^2 \mathbf{v} + (\mathbf{a} \cdot \mathbf{v}) \mathbf{a} - a \mathbf{a} \times \mathbf{v} + \sum_i c_i (\mathbf{m}_i \cdot \mathbf{a}) \mathbf{m}_i \times \mathbf{v} - a \sum_i c_i \mathbf{m}_i \times (\mathbf{m}_i \times \mathbf{v}) + \frac{1}{2} \sum_{ij} c_{ij} ((\mathbf{m}_i \times \mathbf{m}_j) \cdot \mathbf{v}) (\mathbf{m}_i \times \mathbf{m}_j)
\end{align*}
\]

\[
\mu_a = \frac{a^3 + a |\mathbf{a}|^2 - \sum_i c_i [a^2 + (\mathbf{m}_i \cdot \mathbf{a})^2] + a \sum_i c_i (\mathbf{m}_i \times \mathbf{m}_i)^2 - \frac{1}{6} \sum_{ijkl} c_{ijkl} |(\mathbf{m}_i \times \mathbf{m}_j) \cdot (\mathbf{m}_k \times \mathbf{m}_l)|^2}{a^3 + a |\mathbf{a}|^2 - \sum_i c_i [a^2 + (\mathbf{m}_i \cdot \mathbf{a})^2] + a \sum_i c_i (\mathbf{m}_i \times \mathbf{m}_i)^2 - \frac{1}{6} \sum_{ijkl} c_{ijkl} |(\mathbf{m}_i \times \mathbf{m}_j) \cdot (\mathbf{m}_k \times \mathbf{m}_l)|^2}
\]
To show the dependence of Eq. (12) on $g^{\dagger\dagger}$, we plot the detected signal for arbitrarily chosen values of the parameters $g^{\dagger\dagger}$ and $g$. Figure 2(a) shows the magnetic contribution to the total signal using $g^{\dagger\dagger}=(1.5+i0.1)g$, for different values of the interface conductance $g$. The width of the curves increases from the top trace ($g=0$) to the bottom one ($g=16$), reflecting the fact that with increasing interface conductance, more relaxation takes place in the leads. Figure 2(b) shows the signal for fixed $g=1$ and different mixing conductances $2g^{\dagger\dagger}=1.5(1.5+i0.1)k$, with $k$ taking the values 1.5, 5, and 20. Here again the traces broaden, but now the relaxation of the spin is truly due to the mixing term $2g^{\dagger\dagger}$, the third term in Eq. (11). The solid lines represent the precession field in the $z$ direction and dashed lines for the field along $x$. We also note that the maximum of the solid curves shifts to negative fields as a result of the intrinsic precession field proportional to $2g^{\dagger\dagger}$. This is not the case for the dashed traces, because the direction of the contacts’ magnetization leads to total cancellation of the intrinsic precession field of the $x$ component.

The detected precession signal, also in the presence of the mixing conductance terms, can always be expressed as the sum of an “absorptive” (even) term,

$$\frac{1}{\tau_{rel}^2 + \omega_z^2},$$

and a “dispersive” (odd) one,\(^{19}\)

$$-\frac{\omega_z}{\tau_{rel}^2 + \omega_z^2},$$

with $\omega_z=b+\delta\omega_z$ and a suitable choice of $\delta\omega_z$ and $\tau_{rel}^2$. Figure 2(c) shows the absorptive and dispersive terms, plotted for $\delta\omega_z=0$.

### III. SAMPLE FABRICATION

The system under study consists of an aluminum island with lateral dimensions of $400 \times 400 \times 30$ nm. Four cobalt electrodes of different width are connected to the island through tunnel barriers. A typical device is shown in Fig. 1. Devices are fabricated by suspended shadow mask technique and by electron beam (e-beam) lithography. We begin with a trilayer consisting of 1.6-$\mu$m copolymer PMMA/MMA, 40-nm germanium, and 200-nm PMMA deposited in this order on a 500-nm thermally oxidized Si substrate. After e-beam exposure and development of the trilayer,\(^7\) the germanium mask is suspended 1.6 $\mu$m above the substrate. Then 30-nm Al are deposited under an angle to form the island, in an e-beam evaporation system with base pressure of $10^{-6}$ mbar. We notice that changing the evaporation rate from 0.1 to 0.3 nm/sec reduces the Al resistivity by a factor of 2. For aluminum deposited at 0.3 nm/sec, $\rho_{300}$ $K/\rho_{4 K}=2$, and for 0.2 nm/sec, $\rho_{300} K/\rho_{4 K}=1.3$. In the following, all the devices have been deposited at a rate of 0.3 nm/sec, unless indicated otherwise. Next, we oxidize the Al in 0.02–0.2-mbar pure oxygen for 2–5 min to produce tunnel barriers (20–500 $\Omega$ $\mu$m$^2$). The devices are produced with different tunnel barrier transparencies (from 1 to 40 $k\Omega$). Co leads (40 nm thick) are subsequently deposited under a different angle.
The devices are fabricated with decreasing tunnel barrier resistance to determine the lowest transparency for which the tunnel barriers still retain a sizeable spin selectivity. We also started off with the idea of measuring the mixing conductance term. In order to measure \( G^{11} \), \( \tau_{\text{mix}} \) or \( |\omega_{\text{mix}}|^{-1} \) have to be comparable to the relaxation time \( \tau_{\text{rel}} \). It was shown that O. \( G^{11} \)-G \( \approx 0 \), the equality holding true for tunnel barriers. Also, the imaginary part \( \text{Im} \ G^{11} \) for tunnel barriers is of the same order of magnitude as \( G \). The devices we fabricated with the highest transparencies have tunnel barriers of \( G^{11} = 1 \ \text{k}\Omega \) and show a spin-relaxation time of \( \tau_{\text{rel}} = 60 \ \text{ps} \) and an escape time of \( \tau_{\text{esc}} = 10^{3} \tau_{\text{rel}} \); such a system is unsuitable for a measurement of \( G^{11} \).

Tunnel barriers with resistances three orders of magnitude lower could not be fabricated (and probably cannot) in aluminum oxide. The alternative would be to decrease the island volume by a factor 1000, but this is not feasible with this fabrication technology.

IV. SPIN INJECTION EXPERIMENTS

We first review and simplify the expressions that are relevant for our devices. Spin accumulation measurements are done in a four-terminal geometry: we drive a current \( I \) into and out of two electrodes and we detect the voltage \( V \) using the other two electrodes. For the devices with the most transparent tunnel barriers we could fabricate, the mixing term accounts for a correction to the spin accumulation of 10^{-3}. For this reason, we set \( G_{s} = G^{11} = 0 \) in Eq. (12). The following equations are derived from it, after some algebraic manipulation. The spin-dependent contribution to the total signal \( eV_{s} = \mu \cdot d \),

\[
R_{s} = \frac{V_{s}}{I} = \frac{-\tau_{sf}}{\nu_{p}e^{2}V} \mu \cdot d, \tag{15}
\]

in the absence of magnetic field \( \omega = 0 \), where \( s = P_{1}m_{1} \), \(-P_{2}m_{2}\) is the source term and \( d = P_{3}m_{3} - P_{4}m_{4} \) the detector, if current is sent from Co1 to Co2 and voltage is detected between Co3 and Co4. \( \nu_{p} = 2.4 \times 10^{28} \ \text{eV}^{-1} \ \text{m}^{-3} \) is the aluminum density of states at the Fermi energy and \( V \) the volume of the island.

In the presence of a magnetic field, the magnetization perpendicular to the field precesses. When using ferromagnetic electrodes, one has also to be concerned with the stray fields generated by the electrodes themselves, that thread the island. To avoid these, we add an extra term \( \omega_{\text{st}} \) to the external magnetic field \( g \mu_{B} \hat{B} \hat{z}/h = \omega_{\text{st}} \), \( \omega_{\text{st}} = b \hat{z} + \omega_{\text{st}}^{	ext{perp}} \).

In general,

\[
R_{s} = \frac{-\tau_{sf}}{\nu_{p}e^{2}V} \left( s \cdot d + \frac{s \cdot d - (s \times d) \cdot \omega \tau_{sf}}{1 + |\omega|^{2} \tau_{sf}^{2}} \right), \tag{16}
\]

where || means in the same direction as the external field. This is the \( \omega \) direction if also \( \omega_{\text{st}} \) has only a \( \omega \) component, \( \omega_{\text{st},\omega} \). As mentioned before, Eq. (16) can be written as a linear combination of the absorptive and dispersive terms (and a constant term). Eqs. (13) and (14), shifted in the precession field by \( \omega_{\text{st},\omega} \), with \( \tau_{\text{rel}} = \tau_{sf}^{2} + \omega_{\text{st},\omega}^{2} \).

Equation (16) is not invariant under the reversal of the electrodes’ magnetization \( s \rightarrow -s \) and \( d \rightarrow -d \), because the reversal also produces a change of sign \( \omega_{\text{st}} \rightarrow -\omega_{\text{st}} \neq 0 \). It obeys, however, the reciprocity relation \( R_{s} = R_{c} \) that requires the interchange of voltage and current probes and the reversal of all magnetic fields and magnetizations. In the following we show that we obtain experimentally the same spin signal but only in the constraints given by the reciprocity theorem.

V. MEASUREMENT CONFIGURATIONS

The four cobalt electrodes have different widths, one pair 100 nm wide, the other 500 nm, with the latter having the lowest coercive field. The magnetic shape anisotropy holds the electrodes’ magnetization in the substrate plane, and by applying an in-plane external magnetic field along the electrodes’ direction (the \( y \) direction), we can independently reverse the direction of the magnetization of the electrodes. We identify an antiparallel configuration, in which two electrodes are pointing in the same direction and two in the opposite, and a parallel, in which all four have the same direction, as shown in Fig. 3(a). Here parallel and antiparallel are used as a practical shorthand notation: we will show in fact that the electrodes’ magnetizations are noncollinear. In the anomalous configuration, three electrodes (the two wide and one of the narrow ones) are pointing in the same direction and the fourth narrow electrode is in the opposite direction.

Figure 3(b) shows the three independent electrical measuring configurations. The current \( I \) is sent between \( I^{+} \) and \( I^{-} \) and the detected voltage is \( V = V^{+} - V^{-} \). The plotted signal is
$R = V/I$. In the side configuration, the background signal is the island’s Ohmic resistance. In the diagonal configuration, little Ohmic contribution is expected, owing to the symmetric position of the voltage contacts with respect to the current path. The spin-dependent contribution in the two cases is, however, equal if the island is zero dimensional. On the other hand, the opposite configuration should show small spin signal as the widest electrodes switch at the same time ($s = 0$) and so do the narrow ones ($d = 0$).

We write the total signal as the sum of a spin-independent (Ohmic) and a spin-dependent contribution, $R = R_{\text{Ohm}} + R_s$. $R_{\text{Ohm}}$ is the island four-terminal Ohmic resistance and we assume it to be independent of the magnetic arrangement of the electrodes (we exclude, for instance, the Hall effect).

$R_s$ is the spin-related part. We refer to Fig. 3(c) to illustrate its contribution in the three different magnetic configurations. Suppose for the moment that all electrodes are collinear and the barrier polarizations $P_j$ are all equal. $I^+$ and $I^-$ are the current electrodes, $V^+$ and $V^-$ the voltage probes, and the black dots are the voltages that would be detected if the polarization was $P = 1$. The position of the dot on the $\mu_1$ or $\mu_2$ lines depends on the orientation of the detector. In the antiparallel configuration, a uniform nonequilibrium magnetization in the island is created and $(\mu_1 - \mu_2)/2 \neq 0$. This potential difference is detected at the voltage electrodes and the signal $R_s$ is given by Eq. (16).

In the parallel configuration, there is no net spin accumulation. However, a spin current $I = \sigma P_l \mu d/e$ is injected at $I^+$ and extracted at $I^-$, giving rise to a space-dependent magnetization, $I = -\sigma \nabla \mu$. Recalling that the device is in the parallel configuration, the detected spin related contribution is $P$ times the difference of the spin-up chemical potential at the $V^+$ and $V^-$ positions. The spin signal is a fraction of the Ohmic resistance, $R_s = P^2 R_{\text{Ohm}}$. For $P = 1$, the total resistance doubles because only one spin channel is used, halving the island’s conductance.

In the anomalous configuration, the $V^+$ probe measures $\mu_1$, and $V^-$ detects $\mu_2$. Owing to the symmetric position of $V^+$ and $V^-$ with respect to $I^+$ and $I^-$, both probes measure the same amount of magnetization and the spin-dependent contribution is canceled. $R_s = 0$. In the anomalous configuration, one therefore expects to have the lowest signal, equal to the island’s Ohmic resistance. Standard lock-in techniques are employed, with excitation currents ranging from 5 to 100 $\mu$A and with modulation frequencies between 4 and 10 Hz.

VI. EXPERIMENTAL RESULTS

A spin valve experiment is a four-terminal resistance measurement in one of the three possible configurations, see Fig. 3(b), as a function of the in-plane magnetic field (in the $y$ direction). Spin valve measurements were performed both at 4.2 K and at RT, and precession measurements only at RT. We measured nine devices in total, one at 4.2 K only, two both at RT and 4.2 K, and six only at RT. They all show consistent behavior.

We report here a complete set of measurements on a device with tunnel barriers of $R_1 = 1.5$ k$\Omega$, $R_2 = 0.90$ k$\Omega$, $R_3 = 1.6$ k$\Omega$, and $R_4 = 0.75$ k$\Omega$ at RT. From these, we show that we can derive the magnetization orientation of the magnetic contacts and their polarizations. Comparison measurements on a different device at 4.2 K are shown at the end of this section. We will also discuss the relationship between tunnel barriers’ transparencies and polarization.

To characterize the device, each individual tunnel barrier is first measured: with reference to Fig. 1, by sending a current between Co1 and Co2 and detecting the voltage between Co1 and Co3, we measure tunnel barrier 1. Usually Co1 and Co3 have the same resistance (within 20%) as do Co2 and Co4, because they have nominally the same area.

The $I$-$V$ characteristic of a 1.8-k$\Omega$ tunnel barrier measured at liquid-helium temperature is shown Fig. 4. Positive voltage means Co at higher potential than Al. All the tunnel barriers (TB’s) we measure at 4.2 K (with resistances down to 7 k$\Omega$) show a peak at zero bias and are asymmetric in the applied bias. Variation of the tunnel barrier differential resistance of 10% in the bias range used is visible.

The measurements are organized in the following way: for each measuring configuration, we show one spin valve measurement and three precession measurements for the different magnetic configurations. Figure 5(a) shows measurements at RT for the side configuration. Starting with the magnetic field at 80 mT, with all the magnetic contacts pointing parallel to each other, we sweep the field to negative values. At $-25$ mT, the two larger electrodes flip, the magnetic configuration is antiparallel, and the detected signal increases above the background level by 45 m$\Omega$. Increasing the field further, at $-32$ mT, one of the smaller electrodes reverses, and the signal dips 10 m$\Omega$ below the background level. At $-38$ mT, the second smallest electrode also flips and the signal reaches the background value. The reverse trace shows very similar behavior, the notable difference being a larger peak, about 48 m$\Omega$, and a smaller dip, 6 m$\Omega$. Repeated sweeps give similar results.

Figure 5(b) shows the memory effect, that reflects the hysteretic behavior of the electrodes. Starting with the system in the antiparallel configuration at $+30$ mT, we sweep the field toward negative magnetic fields. The electrodes stay in the
antiparallel magnetic configuration until we reach \(-25 \text{ mT}\), at which point the largest electrodes switch parallel to the smallest ones. In the reverse sweep, at \(+20 \text{ mT}\) the largest electrodes flip again, returning the initial configuration. The second trace is the memory effect in the anomalous configuration. Suppose Co1, Co2, and Co3 are parallel to the \(y\) direction and Co4 is opposite. Starting at \(+33 \text{ mT}\) (and \(186 \text{ m}\Omega\)), we sweep the field towards negative fields. At \(-25 \text{ mT}\), the largest electrodes Co1 and Co3 flip, now pointing in the \(-y\) direction and parallel to Co4: this is still an anomalous configuration. Upon reaching \(40 \text{ mT}\), the smallest electrode Co3 flips parallel to the other three and the detected signal reaches the background level.

In a precession experiment, we apply an external magnetic field perpendicular to the sample (in the \(z\) direction), with the in-plane field switched off. Figure 5(c) shows precession measurements for the three magnetic cases, parallel, antiparallel, and anomalous configurations. In both antiparallel and anomalous there is a noticeable dependence of the signal on the magnetic field, whereas in the parallel case little modulation is seen. From the smoothness of the curve, we conclude that the contacts’ domains do not flip irreversibly in the direction of the external field, up to fields of \(280 \text{ mT}\). At higher fields, however, the magnetization of the end domains of the strip is unstable and tends to flip to a different configuration irreversibly, resulting in sudden jumps of the signal. One could also think of doing precession measurements with an in-plane magnetic field, perpendicular to the leads, in the \(x\) direction. The left inset in Fig. 5(c) shows the result of such a measurement, a sweep from \(+40\) to \(-60 \text{ mT}\) and back to \(+60 \text{ mT}\): at fields as low as \(30 \text{ mT}\), the electrodes’ domains begin to rotate and the signal deviates from a smooth curve.

The signal is fit with Eq. (16), written in a way suitable for interpolation, and similar to Eq. (2) of Ref. 9:

\[
R = \frac{\mathbf{s}_i \cdot \mathbf{d}_i}{\gamma_D V} \left( \frac{\cos \phi - \omega_z \sin \phi}{1 + \omega_z^2} + R_{\text{back}} \right) + \tilde{R}_{\text{back}}.
\]  

(17)

The background term \(R_{\text{back}}\) accounts not only for the Ohmic resistance, but also for the magnetization that is injected parallel to the applied field and that does not precess. In fact, from the geometry of the device, the end domain of the contacts are pointing slightly upwards.

Note that only in the case \(\omega_{z,\perp} = 0\), \(\phi\) is the angle between injector and detector (it is actually the projection of the angle on the plane perpendicular to \(z\)), and \(\tilde{\tau}_{sf} = \tau_{sf}\). Here, we allow for a stray field through the sample only in the \(z\) direction: \(\omega_z = g \mu_B |\mathbf{B}| / h + \omega_{st, z}\) and we assume \(\tilde{\tau}_{rel} = \tau_{sf}\).

For the antiparallel case of Fig. 5(b) we find \(\tau_{sf} = 62 \pm 2 \text{ ps}\) \(\phi = (-0.06 \pm 0.01)\pi\), \(\omega_{st, z} = -14 \pm 4 \text{ mT}\), and a background \(R_{\text{back}} = 192 \pm 1 \text{ m}\Omega\). Using the diffusion constant for the aluminum \(D = 5 \times 10^{-3} \text{ m}^2/\text{s}\) found from resistivity measurements, the diffusion time is \(\tau_{diff} = L^2 / D \approx 30 \text{ ps}\), shorter than \(\tau_{sf}\). The spin-diffusion length is \(\lambda_s = \sqrt{D \tau_{sf}} = 550 \text{ nm}\).

We now give a first estimate of the polarization \(P\): assuming that only the widest electrodes’ magnetizations are rotated by \(\phi\), \(|\mathbf{s}_i| = |\mathbf{d}_i| = 2P \cos(\phi/2)\), we find \(P = 7\%\). Parallel and anomalous configurations differ by about \(6 - 10 \text{ m}\Omega\) in the spin valve measurement, Fig. 5(a), and \(12 \text{ m}\Omega\) in the precession trace, whereas the spin current accounts for only \(P^2 R_{\text{ohm}} = 1 \text{ m}\Omega\). The precession data for the anomalous configuration indicate that accumulation also occurs, but accounts for most of the signal.

We fit the signal in the anomalous configuration with Eq. (16), but now fixing \(\tau_{sf}\) to the value found in the (side) antiparallel case. We find \(\phi = (0.11 \pm 0.04)\pi\), \(\omega_{st} = 0 \pm 8 \text{ mT}\) and \(R_{\text{back}} = 197 \pm 1 \text{ m}\Omega\).

From the precession measurements, we work out the magnetic configuration of each electrode. We note first that for the function

\[
\mathbf{s}_i \cdot \mathbf{d}_i \left( \frac{\cos \phi - \omega_z \sin \phi}{1 + \omega_z^2} + R_{\text{back}} \right) + \tilde{R}_{\text{back}}.
\]
The spin accumulation in the side configuration is comparable to that in the parallel configuration. In fact, the ratio between magnetic signals in the parallel and antiparallel configurations differs by 5–8 mV. We also test the prediction of the reciprocity theorem, implying that the signal is odd in the magnetic field, and precession measurements show variations between successive measurements, spanning from 7 to 15 mT and from 0.04 to 0.07 μT. The signal in the anomalous opposite configuration shows a magnetic-field dependence [see Fig. 8(b)]. The most notable feature is that the signal is odd in the magnetic field, implying that s and d are almost perpendicular to each other. We fit the signal by fixing the spin-relaxation time τ_sf = 62 ps as found from the side configuration and find W = (−0.35 ± 0.01) μT, W = −23 ± 7 mT, and W = 200 ± 1 mΩ.

We now compare the predicted signal in the side antiparallel configuration (1+κ) and in the anomalous opposite configuration 2 × 2κ sin φ ′ (1+κ)²/4κ sin φ ′ = 8.1, comparable to the amplitudes ratio of the measured signal 55 mV/10 mΩ = 5.5.

In the case of magnetic electrodes, one has...
also to reverse their magnetizations. Figure 9 shows measurements of the spin accumulation for different electric and magnetic configurations. We proceed as follows: with the external field applied in the positive $y$ direction, we set the contacts in the antiparallel configuration. We then measure the precession signal (curve 1). Next, we exchange the current and voltage probes and we repeat the measurement (curve 2), this time applying the external magnetic field in the $-z$ direction. Next, with the leads interchanged, we apply the field in the $-y$ direction and set the device’s magnetic configuration to antiparallel. We then measure the precession signal, again with the external field in the $-z$ direction (curve 3). We see that curves 1 and 3 are identical. Curve 2 is shifted in magnetic field and its maximum is 2 mV higher than the other two curves. In fact, in the presence of a $\omega_o \neq 0$, the last term in Eq. (16) is not invariant if we simply exchange $s \rightarrow d$ without flipping their directions, $s \rightarrow -s$ and $d \rightarrow -d$. A small in-plane stray field of $\approx 20$ mT is enough to account for a difference of 2 mV.

We also note that the spin valve traces for all magnetic configurations at zero magnetic field are offset from one another by about 1–2 mΩ. We believe that again the last term of Eq. (16) is responsible, as reversing the electrodes’ magnetizations $m_j \rightarrow -m_j$, also causes $\omega_o$ to reverses. We can exclude a Hall effect generated by the leads’ magnetic field. In fact, taking the Hall resistance $R_H = -3.5 \times 10^{-11} \Omega \cdot m/T$ for Al in the low-field limit,25 the Hall contribution would be $R_H B/d \approx 0.1$ mΩ, using the thickness of the island $d = 30$ nm and a field of 100 mT, which is too small to explain the difference.

As a comparison, Fig. 10 shows measurements at 4.2 K in the (a) side, (b) diagonal, and (c) opposite configurations. The reversal of the widest electrodes is steplike. In the diagonal configuration, the left and right peaks have different heights, probably due to incomplete switching of one of the contacts.

We have also measured two devices with tunnel barriers in the range 2–4 kΩ, and found a spin signal of 80 mΩ. For more transparent interfaces, 0.8–1.6 kΩ (two devices), the spin signal is 55 mΩ. For the last four devices, the spin-relaxation time is $\tau_{sf} = 60 \pm 4$ ps. Two devices (Al deposition rate 0.2 nm/sec) were measured both at 4.2 K and at RT: one device, with tunnel barriers of 5–11 kΩ, gave a spin signal...
of 90 mΩ at RT and 250 mΩ at 4.2 K, the other with tunnel barriers 15–35 kΩ, 150 mΩ at RT, and 300 mΩ at 4.2 K.

We note that the polarization of the interface decreases from 10.5% for the highest resistance interfaces to 8% (if we assume that the relaxation time is the same for all devices). Although these values are unequivocally lower than spin polarization measurements with superconducting aluminium, we see that the aluminium oxide interfaces can be made transparent enough without losing the polarization completely.

Jedema et al.7 have performed for Al/Al2O3/Co one-dimensional (1D) structures, spin valve, and precession measurements. E-beam evaporation was used (the same evaporating machine) to deposit the metals. They also reported spin-flip times of 50 ps but a polarization of the tunnel barriers at RT of 11%, slightly larger than what we found, based on the fit to the experimental traces with a time-of-flight 1D model that takes the diffusion constant as an independent parameter. They also found, from precession measurements at 4.2 K, that the spin polarization of the tunnel barriers increases to 13% and the spin-relaxation time doubles.

As we were not able to perform precession measurements at 4.2 K (due to technical difficulties), we could not determine separately the value of the spin-relaxation time and the spin polarization of the injector and detector. For this reason, we cannot conclude which is the main mechanism of relaxation, whether phonon or impurity induced, and to compare with the theoretical calculations of Fabian and Das Sarma.27 Nevertheless, our spin valve results at 4.2 K are consistent with those of Jedema et al.

VII. CONCLUSION

Spin accumulation is analyzed for zero-dimensional systems, in which the electron spin-diffusion time $\tau_{\text{diff}}$ is shorter than the spin-relaxation time $\tau_{\text{rel}}$ and the spin accumulation can be considered uniform. In the system under study, spins are injected into a small island of normal metal through ferromagnetic contacts, and the resulting magnetization is electrically detected by means of other FM contacts. We have theoretically modeled the island using the finite element theory of Brataas et al.11 We have shown that the presence of the leads affect the spin accumulation by making available extra channels of spin relaxation. In particular, the mixing term $G^{\perp}$ is selectively relaxing spins with orientation perpendicular to the electrode magnetization. The expression we derived for the spin accumulation in the island is valid in the case of negligible spin accumulation in the FM contacts.

Experimentally, we have fabricated a small island of aluminium with all dimensions (400×400×30 nm) smaller than the spin-relaxation length ($\lambda_{sf} = 550$ nm at RT). Transparent tunnel barriers between the island and the FM electrodes provide a spin-dependent resistance that is much higher than all the other (spin independent) resistances in the system, so as to overcome the conductivity mismatch. Because of the lateral dimensions of the island compared to the spin-flip length, only pure spin accumulation occurs in our device: the spin signal can therefore be described in terms of the relative orientations of the magnetic electrodes. Spin valve and spin precession measurements were presented for different electrical configurations. The peculiarity in the experiments is that the Ohmic drop across the island is smaller than the spin signal.

In spin valve and precession measurements, we extract the polarization of the tunnel barriers and the spin-flip time. The Al2O3 tunnel barriers, with resistances of 20–100 $\Omega$ μm2 still present a certain degree of polarization, $P = 8\%$. The spin-relaxation time at room temperature was found to be $\tau_{sf} = 60$ ps.

The presence of tunnel barriers confine the electrons inside the island and they tunnel out of the system long after having lost their spin information: in fact, the escape time is three orders of magnitude larger than the spin-flip time. With our lateral devices, it is not possible to directly measure the spin mixing conductance.

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10 T. Valet and A. Fert, Phys. Rev. B 48, 7099 (1993); P. C. van Son,


14 For clarity, we have removed from the micrograph the shadow replicas, as these are not in electrical contact to the device and do not affect the system.

15 The spin accumulation is assumed to have only component along the magnetization axis, $\mu^F = m |\mu^F|$, because the perpendicular component is rapidly averaged out by the large exchange energy in the ferromagnet.

16 For intermetallic (clean) contacts, the Sharvin resistance has to be subtracted, see G. E. W. Bauer, Y. Tserkovnyak, D. Huertas-Hernando, and A. Brataas, Phys. Rev. B 67, 094421 (2003).


20 $2 \operatorname{Re} G_\uparrow = G + (e^2/h) \sum_{m} |r_m^\uparrow - r_m^\downarrow|^2 \gg PG$, see Ref. 11.


22 Note that the tunnel barriers of the narrowest electrodes have higher resistance than the other two; this is due to a small misalignment during metal deposition. The resistances of largest electrodes are equal and so are those of the narrowest ones, though.

23 In the equivalent configuration (in the sense of the reciprocity theorem, with current and voltage probes interchanged, and magnetizations reversed), a spin accumulation is present, but it is not detected because the voltage electrodes are parallel to each other.

24 The interpretation we gave in Ref. 9 of the difference between antiparallel and anomalous signals as caused by the spin current is not correct.

